

Integrated Chatter Avoidance and Minimum Quantity Lubrication Conditions for Chatter Vibration Problem in the Machining Process

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Abstract

This paper presents an experimental validation to compare stability lobes diagram between flood and minimal quantity lubrication condition in milling. The cutting condition is the most important factor contributing the machined work piece surface and in determining the acceptable cutting parameters for high productivity in metal cutting industries. Analytical and experimental identifications of the chatter frequencies in milling processes are presented. In the case of milling, there are several frequency sets arising from the vibration signals, as opposed to the single well-defined chatter frequency of the unstable turning process. Frequency diagrams are constructed analytically and attached to the stability charts of mechanical models of high-speed milling. The corresponding quasiperiodic solutions of the governing time-periodic delay-differential equations are also identified with some milling experiments in the case of highly intermittent cutting. The predicted stability lobes are compared with the micro-milling force signal transformed into the frequency domain. It is observed that the predicted stability limits result in good correlation with the experimentally obtained chatter free conditions.

Introduction

In the aerospace, automotive, mould/die and general manufacturing industries, there is great pressure to ensure lower cost, greater productivity and improved quality in order to encourage economic growth. However, machining productivity using a high material removal rate is inhibited by the dynamic deflection of tool and workpiece systems, which generates an unstable cutting force. This causes sudden large vibration amplitudes where energy input exceeds the energy dissipated from the system, producing chatter. Chatter is a self-excited type of vibration that occurs in metal cutting if the chip width is too large with respect to the dynamic stiffness of the system, especially when machining with a high material removal rate. In milling processes, the chip width is the axial depth of cut parameter. This produces a poor surface finish and high tool wear and can even damage machine tools as a result of the regenerative effect, the loss of the contact effect and the mode coupling effect. Regenerative chatter is perhaps the most common form of chatter [3] and will be the focus of this paper. The regenerative chatter stability boundary is known as the stability lobe diagram and is a function of depth of cut and spindle speed.

To predict the stability diagram, researchers have created various types of chatter prediction models, particularly time domain simulation [4], analytical solution of delay differential equations with time periodic coefficients [5], time finite element analysis (TFEA) [6] and semi-discretisation method (SDM) [7]. For chatter suppression, passive and active methods including vibration absorbers, damping, varying spindle speed and others has been applied. Passive methods are often suitable for a wide range of frequencies and machines compared to active methods.

Nowadays, there are critical needs to reduce the usage of cutting fluid in machining process in order to reduce the environmental burden and economic cost [8]. The rapid wear rate of cutting tools due to high cutting temperature is a critical problem to be solved in high-speed machining (HSM) of

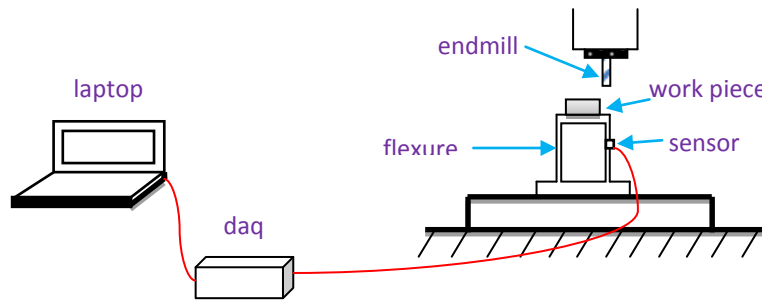
hardened steels. Near-dry machining such as minimum quantity lubrication (MQL) is regarded as one of the solutions to this difficulty. Comparing with dry cutting, the tool performance can be enhanced by MQL under all cutting speeds in this study. It is found that MQL can provide extra oxygen to promote the formation of a protective oxide layer in between the chip–tool interface. This layer is basically quaternary compound oxides of Fe, Mn, Si, and Al, and is proved to act as diffusion barriers effectively. Hence, the strength and wear resistance of a cutting tool can be retained which leads to a significant improvement of tool life. It is found that there exists an optimal cutting speed at which a stable protective oxide layer can be formed. When cutting speed is lower than this speed, there is less oxide layer and the improvement of tool life is less apparent. As the cutting speed is far beyond the optimal value, the protective layer is absent and the thermal cracks are apt to occur at the cutting edge due to large fluctuation of temperature. Resultantly, application of MQL is inappropriate in the extreme high-speed cutting condition irrespective of its little increase in tool life.

Furthermore, in MQL condition, which has cooling and lubricating effects, was found to have more significant influence in improving the tool life as compared to dry condition and its technique not only has cooling and lubricating effects on Nanocomposite coated tool, but also helps to form powerful protective layer [9]. Generally speaking, the cutting fluid applied in the machining process is considered to act as cooling and lubricating agent, hence the cutting temperature can be reduced and the tool life and machined surface finish can be improved. However, in the intermittent cutting such as milling operation, especially in high-speed cutting, the large fluctuation of cutting temperature could cause thermal cracks on the cutting edge and subsequently leads to failure of a cutting tool due to edge fracture [10]. Besides, there are serious environmental pollution and waste disposal problems when flood coolants are used. In order to alleviate the above-mentioned negative effects, near-dry machining such as minimum quantity lubrication (MQL) has been developed and introduced in last decade. MQL properly employed can replace the flooded coolant/lubricant environment which is presently employed in most of the cutting/machining applications; thereby not only the machining will be environmental friendly but also will improve the machinability characteristics [11].

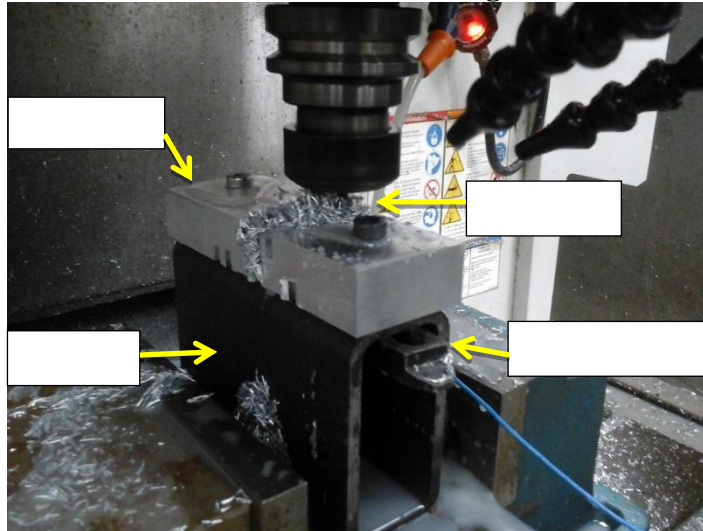
Experimental setting

A VF-1 three-dimensional vertical machining centre produced by Haas Automation, Inc. was selected for the experiments, having a maximum spindle speed of 8100 rpm. The flexure consists of a flexible steel base that was machined from a rectangular cross-section beam welded to a rigid steel base and cutting specimen mounted on top as used by Huyanan and Sims [41]. A 150.0 x 50.0 x 50.0 mm³ aluminium (7075-T6) cutting specimen was mounted on the flexure. This was to be down-milled at 10 percent radial immersion using a 5 mm diameter 4 flute end mill cutter. The tool was either of regular helix/pitch geometry, or optimised geometry using the procedure outlined previously. A set of spindle speeds and axial depths of cut were tested to determine if the cutting was stable or unstable. At the end of each cutting test, it was necessary to perform a clean-up pass to ensure a sufficient free surface for a later test.

During each cutting test, the flexure acceleration was measured the occurrence of chatter, using a piezoelectric accelerometer (PCB 356C21) connected to a DAQ DASylab 10.0 and laptop as shown in Figure 1.1. In addition, a Fast-Fourier Transform (FFT) method in Matlab was applied to the acceleration time samples to illustrate the acceleration spectra, using a Hanning window to reduce signal leakage.



a) Schematic Diagram



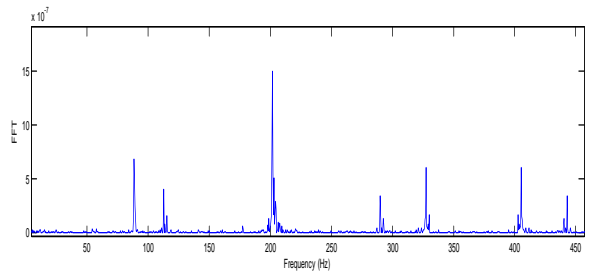
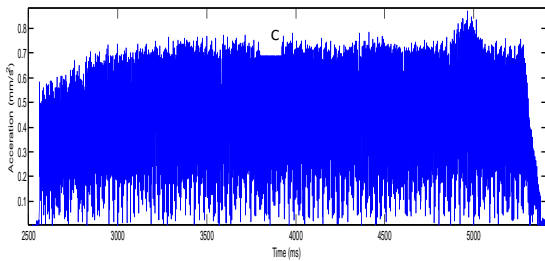
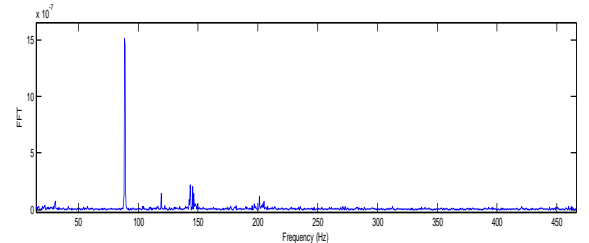
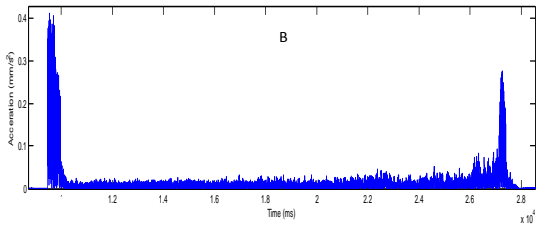
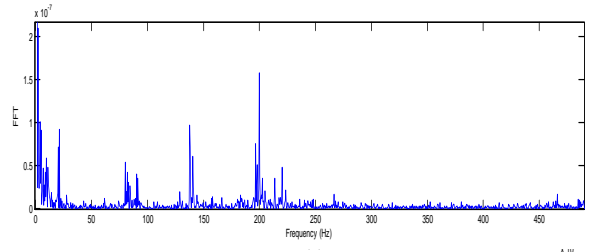
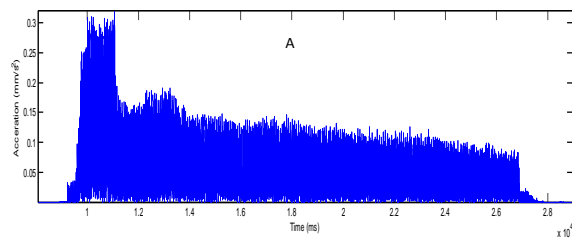
b) Sensor Location

Figure 1.1 Arrangement for optimised tools experimental validation

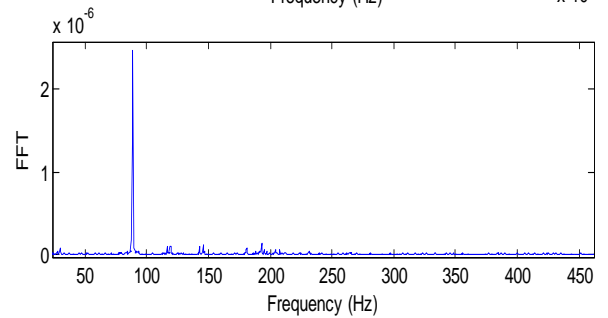
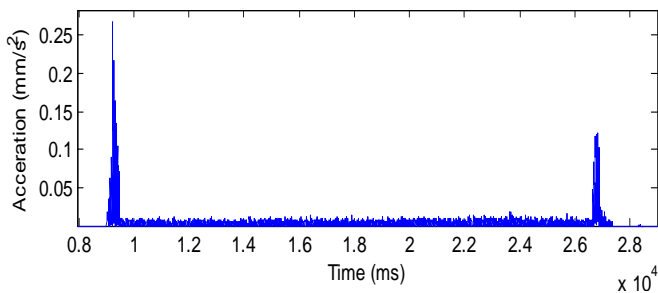
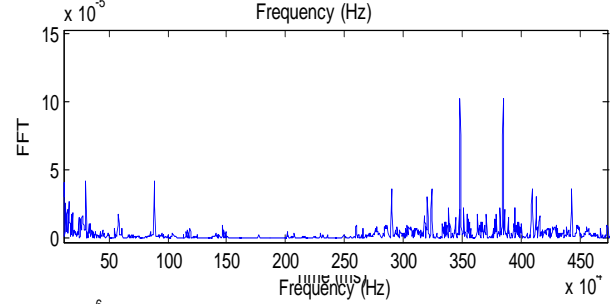
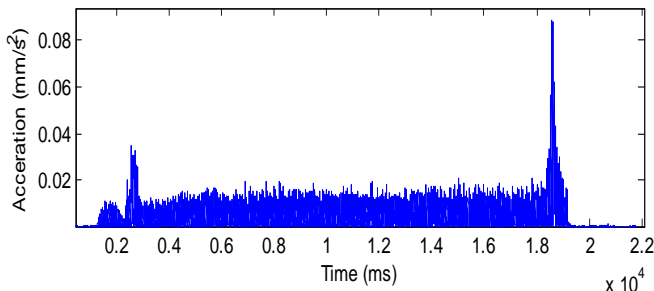
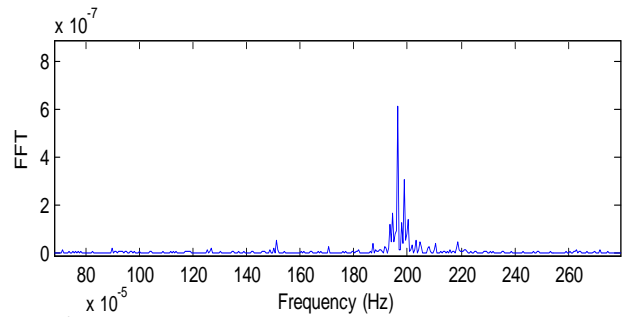
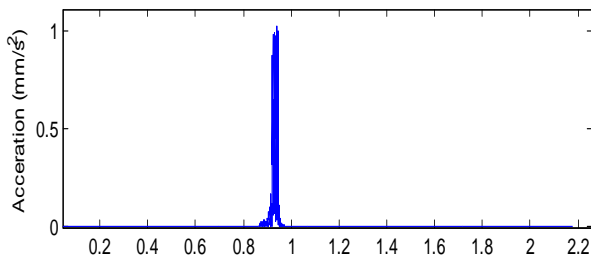
Acceleration signal identification

For the down-milling operation of the regular 4-flute end mill, the acceleration signals were measured for regular and optimised tools performance. Figure 1.2 shows the cutting tests were carried out in 3 cases for flood conditions: A (2750 rev/min, 5.0 mm), B (2750 rev/min, 10.0 mm) and C (5000 rev/min, 7.5 mm). For the minimal quantity lubrication condition, Figure 1.3 shows the results for 3 cases: D (1750 rev/min, 10.0 mm), E (2750 rev/min, 7.5 mm) and F (5500 rev/min, 7.5 mm). Stable or chatter free cutting is demonstrated in cases A and C, as shown in Figures 1.2 respectively.

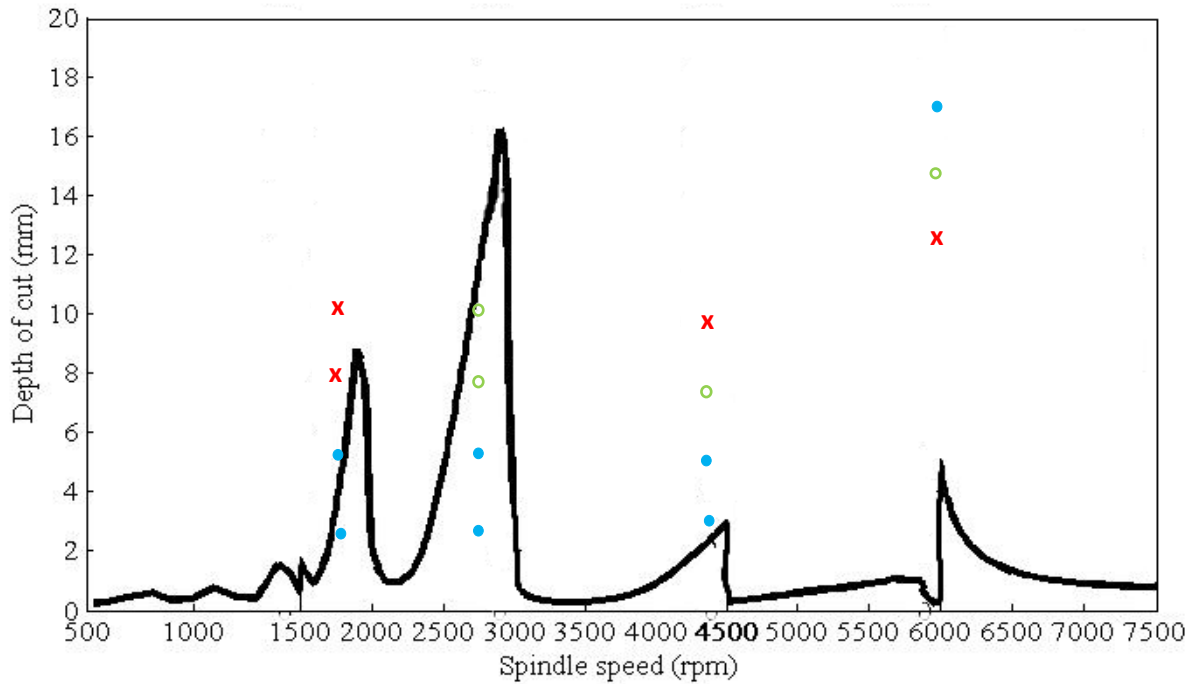
The FFT spectrum shows the frequency is dominated by tooth passing frequencies. These frequencies are lower than the flexure frequency, which related to cutting forces for each tooth beating the work piece. However, chatter cutting is demonstrated in cases B, D and F as shown in Figures 1.2 and 1.3, respectively. The FFT spectrum shows the frequency is dominated by tooth passing frequencies. These frequencies are lower than the flexure frequency, which related to cutting forces for each tooth beating the work piece. For example of FFT spectrum in Figure 1.2 and 1.3 (cases B, D and F), the chatter frequency was closed to the flexure natural frequency.



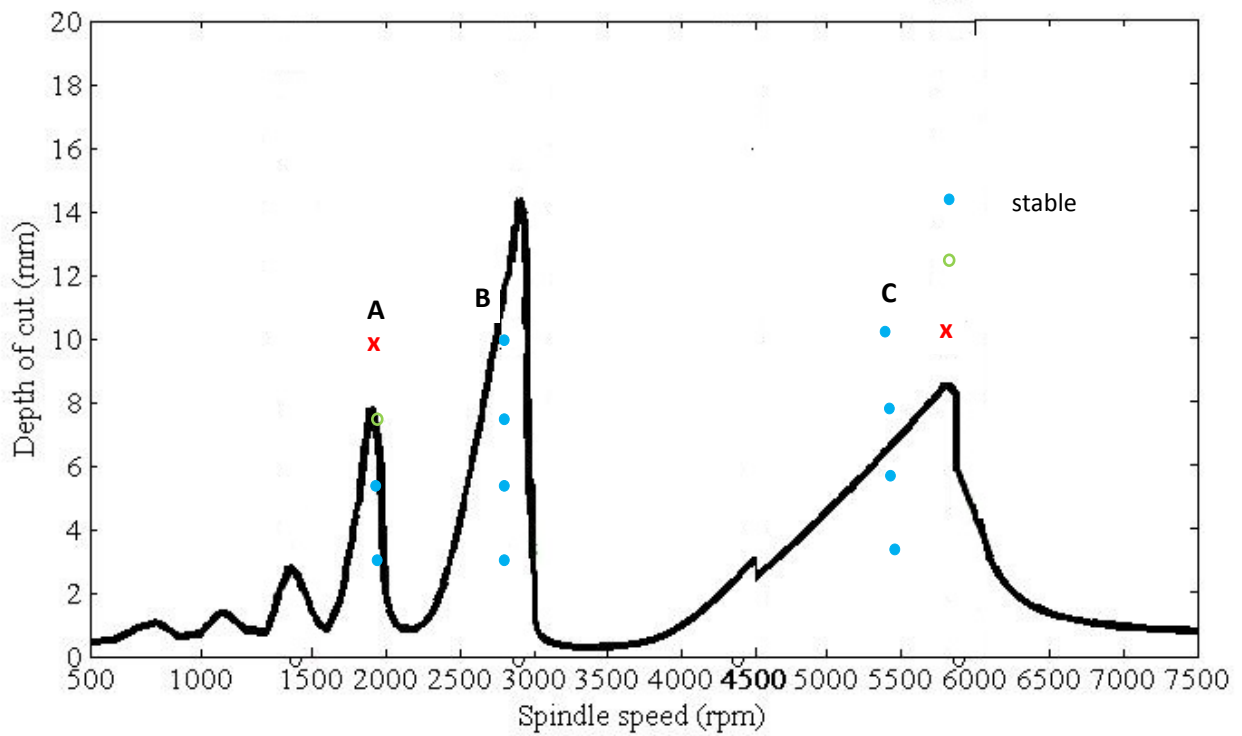
1.2 1/Rev and FFT-Spectrums for points A, B and C on flood condition



1.3 1/Rev and FFT-Spectrums for points D, E and F on MQL condition



1.4a) Stability lobes diagram of 500 – 7500 rev/min for flood condition



1.4b) Stability lobes diagram of 500 – 7500 rev/min for MQL condition

Chatter stability results

From identification of acceleration signal, cutting condition during experiment for each case is then obtained. Both theoretical prediction and experimental results were compared for both tools and their chatter stability diagrams are now presented. Using SDM, the flood cutting condition chatter stability was predicted and superimposed with experimental stability results at 10 percent radial immersion, as shown in Figure 1.4a. It can be clearly seen that there is an unstable area at high depth of cut, with critical depth of cut 10.0 mm, mostly at high spindle speed (1750-5750 rev/min).

For the down-milling operation with minimal quantity lubrication conditions of the regular 4-flute end mill, the result indicates a good agreement between predicted stability and experiment, as shown in Figure 1.4b. Stable or chatter free cutting conditions were shown outside the boundary of unstable regions. However, at high spindle speed, resonance occurred due to similarities of the chatter and spindle frequencies. It can be seen that the critical depth of cut for regular or original cutter was experimentally confirmed to be less than 2.5 mm.

Discussion

The stability of the process is obtained for a wide range of edge radii, feed rates and run-out lengths. The results have been compared with experimentally measured force signals transformed into the frequency domain where good correlation between modelled and experimental results has been obtained. It can be seen that the optimised tool experimental stability results have been accurately predicted by SDM algorithm. These frequencies are lower than the flexure frequency, which related to cutting forces for each teeth beating workpiece. The resonance corresponds to chatter frequency and the tooth passing frequency located close to each other.

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