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Hybrid Harmony Search Algorithm with Grey Wolf Optimizer and Modified Opposition-based Learning

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ABSTRACT Most metaheuristic algorithms, including harmony search (HS), suffer from parameter selection. Many variants have been developed to cope with this problem and improve algorithm performance. In this paper, a hybrid algorithm of HS with grey wolf optimizer (GWO) has been developed to solve the problem of HS parameter selection. Then, a modified version of opposition-based learning technique has been applied on the hybrid algorithm to improve the HS exploration because HS easily gets trapped into local optima. Two HS parameters were automatically updated using GWO, namely, pitch adjustment rate and bandwidth. The proposed hybrid algorithm for global optimization problems is called GWO-HS. GWO-HS was evaluated using 24 classical benchmark functions with 30 state-of-the-art benchmark functions from CEC2014. Then, GWO-HS has been compared with recent HS variants and other well-known metaheuristic algorithms. Results show that the GWO-HS is superior over the old HS variants and other well-known metaheuristics in terms of accuracy and speed process.

INDEX TERMS Computational Intelligence, Grey wolf optimizer, Harmony search, Hybrid algorithm, Metaheuristic, Optimization algorithm, CEC2014.

I. INTRODUCTION

Solving the NP-hard problem using an exhaustive search is an impractical technique because of long-time consumption and complex application. A well-known solution to solve the NP-hard problem with minimal time consumption is using a heuristic technique that can find a near-optimal solution. Heuristic algorithm sacrifices optimality or completeness to obtain quickly the best result.

Meta-heuristic algorithms are higher-level heuristic algorithms that can cover a wider range of problems, with a lack of information or high computation time [1]. The main functionality of meta-heuristic algorithms is obtained by merging rules and randomness to simulate natural phenomena, such as physical annealing in a simulated annealing (SA) algorithm [2], the human intelligence in the harmony search (HS) algorithm [3], the biological evolutionary process in an evolutionary algorithm (EA) [4], and animal behavior in Tabu search [5].

The efficiency of metaheuristic algorithms depends on the utilization of explorative and exploitative ranges through the search process [6]. The exploitative process is accomplished by utilizing the information obtained to guide the search toward its goal. The explorative process is the capability of an algorithm to examine uncovered areas quickly within considerable search sizes. Overall performance develops if the balance between these two characteristics is established [7].

Harmony search (HS) algorithm is a well-known metaheuristic algorithm, introduced by Geem et al. [3] by mimicking the musician's process in creating a new musical harmony[8, 9]. The HS algorithm is used in different fields of optimization problems, such as engineering [10, 11], water distribution [12], structural optimization [6], music ensemble [13], and university timetable [14], Software testing [15-18]. Many other applications and variants of the HS algorithm were made according to previous survey articles [19, 20].

The success of using HS in different research fields is attributed to its characteristics. The main advantage of HS is its capability to utilize exploration and exploitation simultaneously through the search process [14].

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Most metaheuristic algorithms, including HS, suffer from parameter selection, and premature convergence. Many variants have been developed to cope with this problem and improve algorithm performance [21-26].

Generally, researchers have two ways of setting metaheuristic parameter values, namely, by using parameter tuning or by using parameter control.

A. PARAMETER TUNING

The use of parameter tuning is achieved by finding the best values for algorithm parameters before running the algorithm to fix the problem. Parameter tuning involves a number of difficulties, such as longtime consumption because of the need to cover all possibilities, which is practically impossible; another difficulty is high complexity because parameters are not independent; moreover, choosing a fixed parameter as optimal value through the search process is against the idea of EA of a dynamic and adaptive process[27].

B. PARAMETER CONTROL

The other way to modify algorithm parameter values is through the search process, which can be accomplished in three ways.

1: **First method:** The algorithm parameter values can be modified using a deterministic function to replace the static value of the parameters in the search process; an example of this process is the improved HS by Mahdavi et al. [21], who replaced the static values of pitch adjustment rate (PAR) and bandwidth (BW) with new functions to modify their values throughout the search process. The following equations present the dynamic BW:

$$C = \left(ln \left(\frac{BW_{min}}{BW_{max}} \right) \div \text{NI} \right)$$
(1)

$$BW(t) = BW_{max} \times e^{(c \times t)}.$$
 (2)

(*BWmin*; *BWmax*) are the minimum and maximum values of BW, t is the current number of iterations. The following equation present the dynamic PAR:

$$PAR(t) = PAR_{min} + \frac{(PAR_{max} - PAR_{min})}{NI} \times t.$$
 (3)

(*PARmin; PARmax*) are minimum and maximum values of PAR, *t* is the current number of iterations, *NI* is the total number of iterations.

- 2: **Second method:** The algorithm can use feedback from the search process to improve the search parameter values, such as updating step size (by decreasing or increasing it) on the basis of the success rate of the search process.
- 3: **Third method**: The third method uses the self-adaptive values of the algorithm parameters. The adapted parameters can change in chromosomes and mutation processes on the basis of the previous results; an

example of this approach is the self-adaptive global best HS algorithm by Pan et al. who constructed the mutated values of harmony memory consideration rate (HMCR) and PAR through the search process.

In the current article, we present a hybrid algorithm of HS and grey wolf optimizer (GWO). GWO is a newly developed algorithm inspired by the hunting and leadership of grey wolf packs [28]. Inspired by the idea of finding the best values using optimization algorithms, GWO was used in the current paper to modify the HS parameters as a self-adaptive process. Hence, instead of tuning the PAR and BW parameters before the search start, the GWO algorithm modifies the parameter values throughout the search process.

To improve HS exploration and avoid premature convergence, a modified version of the original oppositionbased learning (OBL) [29] is implemented in the hybrid algorithm. This paper mainly aims to design, implement, and evaluate a new hybrid algorithm of HS and GWO with selfadaptive parameter selection. This paper also aims to improve HS algorithm exploration using a modified version of the OBL technique.

To evaluate the effectiveness of the suggested hybrid algorithm, the hybrid algorithm has been tested using 24 classical benchmark functions with 30 state-of-the-art benchmark functions from CEC and compared them with previous HS variants as well as with well-known Parametric tests, metaheuristic algorithms. namely, Wilcoxon's rank test and Friedman test, were used. The tests were used to provide an insight into the new hybrid algorithm in contrast to the previous variants and hybrid algorithm at α = 5% significance level. The new hybrid algorithm shows highly competitive results in all experiments. To find the best values of harmony memory size (HMS) and HMCR for the hybrid algorithm, some experiments were conducted as presented in the experimental results and analysis section.

The remaining sections of this paper are organized as follows. The original HS and its variants. Then GWO algorithm and modified OBL are investigated. The proposed algorithm is described after that. Then, a section will provide the results and discussion. Finally, a conclusion is provided, and possible future improvements are provided.

II. HS and its Variants

In this part, we will comprehensively describe HS, and different variants were created to overcome the HS variable selection and improve its performance. Some researchers utilized fuzzy logic to automatically update the HS parameters [40]. Mahdavi et al. [21], created a modified variant of HS by adding new functions to modify the HMCR and PAR values throughout the search process. Other researchers, such as Omran et al. [22], modified the search process, which he borrowed from Particle Swarm Optimization [41].

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FIGURE 1. HS Process

A. HS ALGORITHM

The HS algorithm process contains five main steps, as shown in Figure 1:

Step 1: Creating initial values of HS parameters: BW, PAR, HMCR, number of iterations (NI), and HMS. The optimization objective function will be determined in this step either by using the maximum or minimum objective function f(x), which are the benchmark functions used in this paper. X_i is the prospect solution vector from N (all possible solution vectors of X_i , and the X_i value is within (lower and upper boundaries) for all the decision variables.

Step 2: In this step, HM will be initialized within the upper and lower boundary ranges, as shown in the next equation, and X_1 is a random value between 0 and 1.

$$X_i = LB + r_1 \times (UB - LB) \tag{4}$$

Step 3: In this step, the improvisation of new harmony will be performed using a combination of three major parameters, namely, HMCR, PAR, and BW, according to line 9 in Algorithm 1. First, random number X_2 generated between 0 and 1; if X_2 is larger than HMCR, then a new value X_j will be created using Equation 1; otherwise, a random value of X_i will

be chosen from HM. Afterward, another random value r_3 will be generated between 0 and 1; if it is smaller than or equal to PAR, then X_i will be modified using Equation 2, as follows:

 $X'_{i} = X'_{i} \pm BW \times rnd$ (5) **Step 4:** If the newly generated vector X'_{i} is better than the worst vector in the harmony memory, then the worst vector will be replaced with the new vector X'_{i} because of the objective function.

Step 5: The stopping criteria, such as the maximum number of improvisations, should be checked after every improvisation. A detailed description of the HS algorithm is presented in the following pseudocode:

Algorithm1: Harmony Search algorithm improvisation1. while (t < Max number of iterations)</td>

- 2. for $(j = 1 \text{ to } D) = \{D: number of dimensions\}$
- 3. If $(R2) \leq HMCR \{Memory \ consideration\}$
- 4. $x'_i = x_{i,j} \{ i \text{ is a random integer } (1, ... HMS) \}$
- 5. *if* $(R3 \le PAR)$ {*Pitch adjustment*}
- $6. \qquad x_j' = x_j' \pm R4 \times bw$
- *7. end if*
- 8. else
- 9. $x'_i = LB + R5 \times (UB LB))$
- 10. end if
- 11. end for
- 12. Update HM:
- 13. if $(x'_j \text{ better than worst } x_j \{x_j \in HM\})$
- 14. $x_i = x'_i$
- 15. t = t + 1

16. End while

17. return best harmony

B. EXPLORATORY POWER OF THE HARMONY SEARCH ALGORITHM: ANALYSIS AND IMPROVEMENTS FOR GLOBAL NUMERICAL OPTIMIZATION (EHS; 2011)

To improve HS performance, Das et al. [42] conducted a theoretical study of the HS algorithm; another variant of the HS algorithm was introduced. The new variant is compared with other variants of HS and other state-of-the-art optimization algorithms. The new variant shows competitive results. The new variant has the same steps as the original HS except for the BW value, which is updated based on the following equations:

$$BW = k\sqrt{Var(x)} \tag{6}$$

$$Var(x) = \frac{1}{m} \sum_{k=1}^{m} (x_i - \bar{x})^2 = x_i^2 - \bar{x}^2$$
(7)

For the benchmark function, the author suggests using (k = 1, 17); meanwhile, m = HMS, and X is the population average.

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TABLE 1 Benchmark functions (GOV: global optimum value).								
Function	Function Formula	Туре	Range	GOV				
F1: Sphere	$\sum_{i=1}^n x_i^2$	UM	-100, 100	0				
F2: Schwefel's 2.22	$\sum_{i=1}^{D} X_i + \Pi_{i=1}^{D} = X_i $	UM	-10, 10	0				
F3: Step	$\sum_{i=1}^{D} (X_i + 0.5)^2$	UM	-100, 100	0				
F4: Rosenbrock	$\sum_{i=1}^{D} 100 \times (X_i - X_{i-1}^2)^2 + (x_{i-1} - 1)^2$	UM	-30, 30	0				
F5: Schwefel's 2.26	$-\sum_{i=1}^{n} \left[x_i \sin\left(\sqrt{ x_i }\right) \right]$	UM	-500, 500	-12569.5				
F6: Rastrigin	$\sum_{i=1}^{D} (X_i^2 - 10\cos(2\pi x_i) + 10)$	М	-5.12, 5.12	0				
F7: Ackleys	$-20 \exp\left(-0.2 \sqrt{\frac{1}{30} \sum_{i=1}^{D} x^{2}}\right) - \exp\left(\sqrt{\frac{1}{30} \sum_{i=1}^{D} \cos 2x^{2}}\right) + 20 + e$	М	-32, 32	0				
F8: Griewank	$\frac{1}{4000} \sum_{i=1}^{D} x^2 - \Pi_{i=1}^{D} \cos \frac{x_i}{\sqrt{i}} + 1$	М	-600, 600	0				
F9: Rotated hyper-ellipsoid	$\sum_{i=1}^{n} (\sum_{j=1}^{j=i} x_j)^2$	UM	-100, 100	0				
F10: Schaffer	$0.5 + \frac{\sin^2\left(\sqrt{(x_1^2 + x_2^2)} - 0.5\right)}{ 1 + 0.001(x_1^2 + x_2^2) ^2}$	М	-100, 100	0				
F11: Zakharov	$\sum_{i=1}^{n} x_i^2 + \left(\sum_{i=1}^{n} 0.5ix_i\right)^2 + \left(\sum_{i=1}^{n} 0.5ix_i\right)^4$	М	-5, 10	0				
F12: Alpine	$\sum_{i=1}^{n} x_i . \ sin(x_i) + 0.1x_i $	М	-10, 10	0				
F13: Inverted Cosine Wave	$-\sum_{i=1}^{n-1} e^{\left(\frac{-(x_i^2+x_{i+1}^2+0.5x_ix_{i+1})}{8}\right)} \cos 4 \times \sqrt{x_i^2+x_{i+1}^2+0.5x_ix_{i+1}}$	М	-1, 1	0				
F14: Dixon price	$(x_1 - 1)^2 + \sum_{i=1}^n i(2x_i^2 - x_i - 1)^2$	UM	-10, 10	0				
F15: Axis parallel hyper- ellipsoid 2.2	$\sum_{i=1}^{D} i \times X_i^2$	UM	-5.12, 5.12	0				
F16: Sum of a different power 2.8	$\sum_{\{i=1\}}^{\{D\}} X_i^{\{1+i\}}$	UM	-1, 1	0				

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F17: Levy
$$sin^{2}(\pi\omega_{1}) + \sum_{i=1}^{n-1} (\omega_{i} - 1)^{2} [1 + 10 \cdot sin^{2}(\pi\omega_{i} + 1)]$$
 M -10, 10 0
+ $(\omega_{D} - 1)^{2} [1 + i \cdot sin^{2}(\pi\omega_{D})]$
F18: Salomon's 2.8 $1 - cos(2\pi | x |) + 0.1 | x |, |x| = \int_{-1}^{n} x_{i}^{2}$ M -100, 100 0
F19: Pathologic $\sum_{i=1}^{n-1} [0.5 +] \frac{sin^{2} (\sqrt{[100x_{i}^{2} + x_{i}^{2}(s_{1})]}) - 0.5}{1 + 0.001 (x_{i}^{2} - 2x_{ix_{(l+1)}} + x_{l+1}^{2})^{2}}$ M -100, 100 0
F20: Whitley's $\sum_{i=1}^{n} \sum_{i=1}^{n} \left(\frac{(100(x_{i}^{2} - x_{i})^{2} + (1 - x_{i})^{2})}{4000} - cos(100(x_{i}^{2} - x_{i})^{2} + (1 - x_{j})^{2}) + 1 \right)$ M -10, 10 0
 $- cos(100(x_{i}^{2} - x_{j})^{2} + (1 - x_{j})^{2}) + 1 \right)$ M -100, 100 0
F22: Quartic $\sum_{i=0}^{n} ix_{i}^{4} + random(0,1)$ UM -100, 100 0
F23: Penalized 1 $\frac{\pi}{n} \times \{10 \times sin^{2}(\pi y_{1}) +\} \sum_{i=1}^{n-1} (y_{1} - 1)^{2} [1 + 10 sin^{2}(\pi y_{1} + 1) + 0 m) - 100, 100 - 0$
F24: Penalized 2 $\frac{\pi}{n} \times \{10 \times sin^{2}(\pi y_{1}) +\} \sum_{i=1}^{n-1} (y_{1} - 1)^{2} [1 + 10 sin^{2}(\pi y_{1} + 1) + 0 m) - 50, 50 - 0$

С. AN IMPROVED GLOBAL-BEST HARMONY SEARCH ALGORITHM (IGHS; 2013)

El-Abd [24] developed as an improved variant of GHS [22] by focusing on the explorative range at the beginning, and then on the exploitative range at the end of a search. To accomplish this, the author used Gaussian distribution to select the random pitch adjustment, as described in the next Equation:

$$X'_{i} = HM^{r}_{d} + Gauss(0,1) \times BW$$
(8)

Where HM_d^r is a randomly selected value from HM, and Gauss is a random number with a mean of 0 and a standard deviation of 1. For pitch adjustment, the next equation is used as follows:

$$X'_{j} = HM_{d}^{best} + \phi \times BW \tag{9}$$

Where HM_d^{best} is the best value in HM based on the objective function evaluation f(x). The value φ is a random number that is uniformly distributed within the range "-1 to 1". PAR value is decreased within the iterations to achieve great exploitation, as described by [43]. For BW, the author borrowed its formula from the IHS [21] variant. The algorithm was compared with seven previous HS-variants using the CEC 2005 benchmark function.

D. DIFFERENTIAL-BASED HARMONY SEARCH ALGORITHM FOR THE **OPTIMIZATION** OF CONTINUOUS PROBLEMS (DH/BEST; 2016)

Hosein et al.[25] introduced a new HS-variant by modifying two aspects of the original HS. The first modification is applied to the initialization of HS by using a new method to initiate feasible solutions with less randomness. The second modification involves replacing pitch adjustment with the applied to the initialization of HS by using a new method to initiate feasible solutions with less randomness. The second modification involves replacing pitch adjustment with the updated version inspired by the differential evolution (DE) mutation strategy and excluding the BW parameter. The following algorithm describes the new initialization processes, which is implemented by replacing the random value with a new calculation based on HMS:

- Algorithm4: DH/best Initialization (Hosein 2016)
- 1. $for(j = 1 toD) \{D = dimensions\}$
- 2. for(i = 1 to HMS)3. $temp_i = LB + ((i \frac{0.5}{HMS})) \times (UB LB)$
- 4. end for
- 5. Shuffle the temporary array
- 6. for(i = 1 to HMS)
- 7. $HM = temp_i$
- 8. end for
- 9. end for

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Where UB and LB are the upper and lower bounds of the decision variables. The new variant eliminates the requirement of setting BW, and pitches are adjusted based on the distances between the pitches in HM by using DE/best/1 mutation, as described in the following Pseudo-code:

Algorithm5: DH/best Improvisation (Hosein 2016)
1: $for (i = 1 to D)$
2: if $(r(0\sim 1) \leq HMCR)$
3: $X'_i = X_{ij}$ (<i>i</i> is random integer from 1 HMS)
4: $if(r(0\sim 1) \leq PAR)$
5: $X'_i = X_{best} + r(0 \sim 1) \times (X_{r1,l} - X_{r2,l})$
6: $if(X'_i < LB \text{ or } X'_i > UB)$
7: $X'_{i} = r(0 \sim 1) \times (UB - LB) + LB$
8: end if
9: end if
10: else
11: $X'_j = r(0 \sim 1) \times (UB - LB) + LB$
12: end if
13: end for

where UB and LB are the upper and lower bounds of the decision variables, r(0-1) is the random value between 0 and 1, X_{best} is the best X_i in HM based on the objective function, and $X_{r1,J}$ and $X_{r2,J}$ are two random values in the *jth* dimension.

E. A HYBRID HARMONY SEARCH AND SIMULATED ANNEALING (HS-SA; 2018)

New hybrid HS algorithm and SA algorithm were presented by Assad et al. [26], the temperature parameter in SA has been introduced inside the HS algorithm. The new hybrid algorithm adopts a similar process to the original HS, except that it has been updated to accept the poor results of the improvisation process via the probability of the temperature parameter. The temperature starts with a high value to provide high exploration, and it then decreases at each iteration to focus on exploitation through the search process. The new hybrid algorithm provided better results in comparison with the original HS and SA.

III. GWO ALGORITHM

GWO algorithm is a new metaheuristic algorithm developed by Mirjalili et al. [28], GWO has been presented as a swarm-based algorithm that simulates the natural driving life of grey wolves[30, 31]. The GWO algorithm shows high performance in many optimization problems [32-35].

The GWO algorithm divides the population into four groups, namely alpha α , beta β , Delta δ , and Omega ω .

Firstly, random populations of wolves are created. The wolves change their location through the optimization phase on the basis of the fittest wolves, which is α . Consequently, the second and third best solutions are named β , and δ , ω will be guided through the search by those wolves. In order to attack the prey, wolves will encircle the prey as described in the following equations:

$$\vec{D} = |\vec{C} \cdot \vec{X}_p(t) - \vec{X}(t)|$$
(10)

$$\vec{X}(t+1) = \vec{X}_p(t) - \vec{A} \cdot \vec{D}$$
(11)

 \vec{X}_p marks the location vector of the prey, and \vec{X} marks the location vector of the grey wolf. \vec{C} and \vec{A} represent the coefficient vectors, whereas *t* indicates the current iteration value. \vec{C} and \vec{A} values are calculated using the following equations:

$$\vec{A} = 2\vec{A} \cdot \vec{r}_1 - \vec{a} \tag{8}$$

$$\vec{C} = 2. \vec{r}_2 \tag{9}$$

where \vec{r}_1 and \vec{r}_2 are random vectors in (0,1), and \vec{a} decreased from 2 to 0 through iterations.

The α , β , and δ values will be the best solution acquired thus far. Then, all the other values (wolves) are considered as ω and will be relocated with respect to α , β , and δ . The updated value of the wolves is based on the following equations:

$$\vec{D}_{\alpha} = |\vec{C}_1 \cdot \vec{X}_{\alpha} - \vec{X}| \qquad (12)$$

$$\vec{D}_{\beta} = |\vec{C}_2 \cdot \vec{X}_{\beta} - \vec{X}|$$
(13)

$$\vec{D}_{\delta} = |\vec{C}_{3} \cdot \vec{X}_{\delta} - \vec{X}| \qquad (14)$$

Where \vec{X} is the location of the current solution; \vec{X}_{α} , \vec{X}_{β} , and \vec{X}_{δ} are the α , β , δ locations, respectively; \vec{C}_1 , \vec{C}_2 , and \vec{C}_3 are random vectors between (0 to 2); and \vec{X}_{α} , \vec{X}_{β} , and \vec{X}_{δ} , represent the distance between the current solution and α , β , and δ , respectively. Afterward, the final location of the current solution is calculated using the following equations:

$$\vec{X}_1 = \vec{X}_\alpha - \vec{A}_1 \cdot \vec{(D}_\alpha)$$
(15)

$$\vec{X}_2 = \vec{X}_\beta - \vec{A}_2 \cdot \vec{(D_\beta)}$$
(16)

$$\vec{X}_3 = \vec{X}_\delta - \vec{A}_3 \cdot \vec{(D_\delta)}$$
(17)

$$\vec{X}(t+1) = \frac{\vec{X}_1 + \vec{X}_2 + \vec{X}_3}{3}$$
 (18)

Where \overline{A}_1 , \overline{A}_2 , \overline{A}_3 are random vectors between {-2a, 2a}, where a decreased from 2 to 0, within the course of iteration (t).

The final location will be calculated using Equations (10 to 12). Finally, \vec{A} and \vec{C} assist the exploration and exploitation as random and adaptive vectors, respectively. The entire process is described in algorithm 2.

IV. Modified opposition-based learning technique

The original OBL introduced by Tizhoosh [29], and many variants of OBL developed after that and used by different research areas [36]. Many HS variants and hybridizations utilized the OBL and its variants in the literature [37-39].

In this article we applied a modified version of the original OBL within the HS updating process, to improve the HS exploration, as described in Algorithm 3.

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Algorithm2: Grev wolf algorithm

Alg	orithm2: Grey wolf algorithm
1.	Initialize grey wolf population within the boundaries
$x_i(i$	$= 1, 2, \dots, n$
2.	Initialize A, a and C
3.	Calculate the fitness of each search agent
4.	$x_{\alpha} = best \ search \ agent$
5.	$x_{\beta} = second - best \ search \ agent$
6.	$x_{\delta} = third - best \ search \ agent$
7.	while (t < Max number of iterations)do
8.	for (each search agent)
9.	update the current search agent possition by eq 18
10.	End for
11.	Update A, a, and C
12.	Calculate the fitness of all search agents
13.	Update x_{α} , x_{β} and x_{δ}
14.	t = t + 1
15.	return X _a

In algorithm 3, $x\{d\}$ represents the new improvisation vector, r is a random value between 0, and 1, d is the number of dimensions, and x_i is the modified opposition value. Once the improvisation process of HS creates a new value x_j , the modified opposition will be applied on the new improvisation value x_j in the update section and will replace it if it is better on the basis of the objective function f.

Alg	gorithm3:	Modified	opposition
	(-)	-	-

1.	$x\{d\} =$	$\{x_1, x_2\}$,	x_d	
-					

- 2. r = random value between (0, 1)
- 3. for (i = 1 to d) do
- 4. $\overline{X}_i = -1 \times x\{i\} \times r;$
- 5. $if(f(\bar{x}) < f(x))$
- 6. $\mathbf{x} = \bar{\mathbf{x}}$

V. PROPOSED HYBRID ALGORITHM

A hybrid algorithm is an algorithm that merges two or more algorithms to solve a problem. The goal of this algorithm is to create a new algorithm that combines advantages from these algorithms. The main purpose of this paper is to design, implement, and evaluate a new hybrid algorithm of HS and GWO with a self-adaptive parameter selection, where the benchmark functions are the case studies to evaluate the new proposed algorithm.

Given that the PAR and BW have a high effect on the efficiency of HS [22, 44], we utilize the GWO algorithm to find the right values of PAR and BW through the search process. We use a modified version of the original OBL technique [29] to improve improvisation results because HS suffers from bad exploration, especially if one or more of its vectors are near the local optimum. Meanwhile, we use the static values of 5 and 0.99 for HMS and HMCR, respectively. The new algorithm was tested on the benchmark function and proves the superior performance compared with the previous HS variants and other well-known metaheuristics. Figure 6 presents the general process of the hybrid algorithm, which is described as follows:

1. Hybrid algorithm parameter and population initialization:

- a. Hybrid parameters will be initialized, as described in Table 2: HMCR, HMS, the minimum and maximum value of PAR and BW, number of iterations of HS (HS-NI), GWO number of iterations (GWO-NI), and the number of GWO search agents.
- b. The GWO population will be initialized for PAR and BW within their upper and lower boundaries and represented as two dimensions.
- c. The HS population vectors (for the benchmark functions in this paper) will be initialized using HS initialization process. These vectors will be used as HM through the whole process of the hybrid algorithm.
- 2. Improvisation process:
 - a. In the HS-improvisation process, the HM vectors will be optimized using the objective function (benchmark functions in this paper).
 - b. A modified OBL was used to improve the obtained result, from HS improvisation process, within the updating phase of HS, which is described in Algorithm 3. The final result is sent as a fitness function value of GWO optimization process.
 - c. The GWO improvisation process, as described in Algorithm 2, will be used to improvise the PAR and BW values. The fitness function (as included in line 3 in Algorithm 2) value will be the result of HS improvisation process in every GWO improvisation.
- 3. Results: The best results of the hybrid algorithm will be presented in this phase.

Algorithm 6: Hybrid algorithm GWO-HS

- 1: Define the objective function f(x)
- 2: Initialize HS and GWO Parameters (HMS, HMCR, GWO-Number-of-Agents, HS-NI, GWO-NI)
- 3: Initialize GWO population (PARi; BWi)
- 4: Initialize HS population (Xi)
- 5: while(it < GW0 max iteration)do
- *6: while*(*i* < *search agents*)*do*
- 7: while(d < 2)do (for PAR and BW)
- 8: fitnes = HS()(HS-improvisation)
- 9: Improvise new PAR and BW(using GWO)
- 10: Update Alpha, Beta, and Delta
- 11: Improvise new PAR and BW (using GWO improv
- 12: process)
- 13: *Return best harmony*

The values of *PARi*, *BWi* in Algorithm 6 are random values of *PAR* and *BW* within their lower and upper bounds. Possible solutions for x_i for HS initialization are the random values between the objective function boundaries.

To conclude the whole process, the GOW-initialization will be used to create *PAR* and *BW* possible values (as search agents). HS initialization will be used to initialize the benchmark functions possible solution vectors (as HM). In every iteration of GWO, the GWO-fitness function will be the result of HS optimization using the *PAR* and *BW* values from GWOmemory. HS improvisation will improvise HM values to find

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possible solutions to the benchmark functions. Finally, we included a modified version of OBL technique as part of our hybrid algorithm through HS updating. The modified OBL will improve the exploration of HS and help the algorithm avoid falling in local optima. Figure 6 presents the general structure of the hybrid algorithm process. The pseudo code of Algorithm 6 describes the hybrid algorithm.



FIGURE 6. The general process of GWO/HS hybrid algorithm.

VI. EXPERIMENT RESULTS AND ANALYSIS

In the first section, we investigate HMCR and HMS parameter best values for the hybrid algorithm using the first 15 classical benchmark functions from Table 1. In the second and third sections, we apply the hybrid algorithm to minimize a set of 24 classical benchmark functions, as described in Table 1 and 30 state-of-the-art test cases from CEC2014 [45]. The classical test functions contain unimodal and multimodal functions to provide insight into the hybrid algorithm capabilities to cover different types of problems. The CEC2014 is also a wellknown experimental test for single objective optimization problems that contain shifted, rotated, hybrid, and composition optimization test cases. Friedman test and Wilcoxon nonparametric test at $\alpha = 5\%$ significance level were conducted to evaluate the overall performance of the new hybrid algorithm. All experiments are performed on Microsoft Windows 10 Education in a computer with Intel Core i7 Quad

CPU 4702MQ processor 2.2 GHz with 240 GB SSD hard drive and 16GB DDR3 RAM. All algorithms are coded in Java. The best results obtained from the experiments are highlighted in bold.

A. EFFECTS OF HMS AND HMCR ON THE HYBRID ALGORITHM

To determine the best values of the static parameters of the hybrid algorithm, we investigate the different values of the static parameters, namely, HMS and HMCR. Other parameters of the hybrid algorithm for these experiments are the same as those shown in Table 2. We used the first 15 benchmark functions as described in Table 1 to determine the best values of HMS and HMCR as static values in this article. The total number of improvisations is set to 10^4 for all experiments in this article, except for CEC2014 experiments in which we used 10^6 . The mean and SD are calculated for 30 runs of each function with 30 dimensions. Table 4 presents the results of using different HMS values (i.e., 5, 30, 50, and 100). Meanwhile, *f* presents function.

TABLE 2 PARAMETERS SETTING GWO-HS						
Algorithm	Parameters	Value				
Harmony search	HMS	5				
	HMCR	0.99				
	PAR minimum value	0.1				
	PAR maximum value	0.4				
	BW minimum value	0.1				
	BW maximum value	0.4				
	HS iteration	100				
Grey wolf optimizer	Number of search agents	10				
	iteration	100				
	number of dimensions	2				

 TABLE 3

 Parameters setting for compared algorithms

Algorithm	Parameters	Value
ACS2013	N	5
	GLOBAL MINIMUM	1.0E+20
	PP	0.1
MULTIVERSE2016	Ν	5
	BEST UNIVERSE INFLATION	1.0E+20
	RATE	
ABC2005	Ν	5
	LIMIT2	800
DE1997	Ν	5
	F	0.9
	CR	0.5

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		P	TABLE 4 arameters setting for HS variation	ANTS	
Algorithm	HMS	HMCR	PAR	BW	Other
EHS2011	5	0.99	PAR = 0.33	$BW = k \cdot \sqrt{Var}(x)$	
IGHS2013	5	0.9	$PAR_{min} = 0.01$ $PAR_{max} = 0.99$	$BW_{min} = 0.0001$ $BW_{max} = 0.06$	
DHBest2016	5	0.99	0.9	-	CR=0.5
HS-SA2018	5	0.9	0.3	0.001	α=0.99

TABLE 5 EFFECTS OF HMS ON THE GWO-HS PERFORMANCE (HMCR = 0.99).					TABLE 6 EFFECTS OF HMCP ON THE GWOLHS DEPEODMANCE (HMS -5)						
F	Index	HMS	LOWONDIL	IN ORMANCE (I	inter(= 0.99).	F	Index	HMCR	THE OWO-II	STERIORWARD	E(1103-3).
-		5	30	50	100		muex	0.7	0.8	0.9	0.99
F1	Mean	0.0	0.0	4.7E-147	2.1E-157	F1	Mean	7.0E-24	1.4E-37	3.9E-76	0.0
	SD	0.0	0.0	4.7E-147	2.1E-157		SD	7.0E-24	1.4E-37	3.9E-76	0.0
F2	Mean	0.0	0.0	6.3E-161	2.0E-74	F2	Mean	1.1E-1	9.6E-15	4.3E-70	0.0
	SD	0.0	0.0	6.3E-161	2.0E-74		SD	1.1E-1	9.6E-15	4.3E-70	0.0
F3	Mean	0.0	0.0	0.0	0.0	F3	Mean	0.0	0.0	0.0	0.0
	SD	0.0	0.0	0.0	0.0		SD	0.0	0.0	0.0	0.0
F4	Mean	27.6	27.729	27.738	27.73	F4	Mean	28.05	27.91	27.5	27.6
	SD	27.6	27.729	27.738	27.73		SD	28.05	27.91	27.5	27.6
F5	Mean	-12528	-12500	-12494	-12454	F5	Mean	-10081	-12091	-12552	-12528
	SD	12528	12500	-2494	12454		SD	-10081	-12091	-12552	12528
F6	Mean	0.0	0.0	0.0	0.0	F6	Mean	0.0	0.0	0.0	0.0
	SD	0.0	0.0	0.0	0.0		SD	0.0	0.0	0.0	0.0
F7	Mean	4.4E-16	4.4e-16	4.4e-16	4.4e-16	F7	Mean	3.6E-12	8.3E-13	4.4E-16	4.4E-16
	SD	4.4E-16	4.4e-16	4.4e-16	4.4e-16		SD	3.6E-12	8.3E-13	4.4E-16	4.4E-16
F8	Mean	0.0	0.0	0.0	0.0	F8	Mean	0.0	0.0	0.0	0.0
	SD	0.0	0.0	0.0	0.0		SD	0.0	0.0	0.0	0.0
F9	Mean	0.0	0.0	0.0	0.0	F9	Mean	6.6E-20	4.0E-34	7.1E-15	0.0
	SD	0.0	0.0	0.0	0.0		SD	6.6E-20	4.0E-34	7.1E-15	0.0
F10	Mean	0.06	0.049	0.009	0.06	F10	Mean	8.4	0.79	0.029	0.009
	SD	0.06	0.049	0.009	0.06		SD	8.4	0.79	0.029	0.009
F11	Mean	3.8e-14	4.0e-8	4.0e-2	1.59	F11	Mean	2.59	2.60	7.7E-6	3.8e-14
	SD	3.8e-14	4.0e-8	4.0e-2	1.59		SD	2.59	2.60	7.7E-6	3.8e-14
F12	Mean	1.5e-53	3.2e-107	4.5e-145	0.45	F12	Mean	0.49	0.45	0.062	1.5e-53
	SD	1.5e-53	3.2e-107	4.5 e-145	0.45		SD	0.49	0.45	0.062	1.5e-53
F13	Mean	-26.836	-26.79	26.783	-26.87	F13	Mean	-26.44	-26.73	-26.87	-26.836
	SD	26.836	26.79	26.783	-26.87		SD	-26.44	-26.73	-26.87	26.836
F14	Mean	0.666	0.667	0.666	0.67	F14	Mean	3.08	2.6	0.84	0.666
	SD	0.666	0.667	0.666	0.67		SD	3.08	2.6	0.84	0.666
F15	Mean	0.0	0.0	1.3E-241	1.3E-148	F15	Mean	1.1E-23	1.0E-30	0.0	0.0
	SD	0.0	0.0	1.3E-241	1.3E-148		SD	1.1E-23	1.0E-30	0.0	0.0

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TABLE 7 Mean and SD of the errors of HS variants for (D = 30)F Index Algorithms **IGHS 2013** EHS2011 DHBest 2016 **HS-SA2018** GWO-HS F1 14.613 2.235 e-60 0.0 10.242 0.0 Mean 14.61 SD 2.235 e-60 0.0 10.242 0.0 F2 0.179 Mean 3.484 e-35 0.0 0.851 0.0 0.179 SD 3.484 e-35 0.0 0.00.851 F3 20.0 0.0 0.0 Mean 0.0 11.766 SD 0.0 20.0 0.0 11.766 0.0 F4 393.048 Mean 28.712 28.767 553.709 27.766 393.048 SD 28.712 28.767 553.709 27.766 F5 -12539.117 -10238.560 -12565.425 -12542.17 -12540.709 Mean 12539.117 SD 10238.560 12565.425 12542.17 12540.709 F6 Mean 0.0 3.152 0.335 1.449 0.0 3.152 SD0.0 0.335 1.449 0.0 F7 1.841 5.417 e-15 4.440 e-16 1.610 4.440 e-16 Mean 1.841 SD 5.417 e-15 4.440 e-16 1.610 4.440 e-16 F8 1.050 Mean 8.924 e-4 0.0 1.103 0.0 SD 8.924 e-4 1.050 0.0 1.103 0.0 F9 70.978 11.881 0.0 Mean 0.092.409 70.978 SD 11.881 0.0 92.409 0.0 F10 0.441 Mean 0.016 0.155 0.405 0.009 0.441 SD 0.016 0.155 0.405 0.009 F11 975.251 9.206 e-5 57.17 24.633 1.002 e-5 Mean 975.251 1.002 e-5 SD 9.206 e-5 57.17 24.633 F12 0.189 Mean 5.954 e-4 0.032 0.068 1.153 e-62 0.189 SD 5.954 e-4 0.032 0.068 1.153 e-62 F13 -26.875 -26.530 -26.753 Mean -26.786 -26.842 26.875 SD 26.530 26.786 26.842 26.753 F14 Mean 0.697 4.555 10.520 7.625 0.666 4.555 SD 0.697 10.520 7.625 0.666 F15 1.45 e-5 0.033 Mean 0.032 0.10 0.0 1.45 e-5 SD 0.032 0.033 0.10 0.0 F16 4.692 e-14 Mean 3.250 e-10 1.785 e-8 1.70E-16 0.0 SD 3.250 e-10 4.692 e-14 1.785 e-8 1.70E-16 0.0 F17 0.785 1.587 2.869 0.043 0.305 Mean 0.785 SD 2.869 0.043 0.305 1.587 F18 3.506 0.103 0.0 0.0 Mean 1.867 3.506 SD 0.103 0.01.867 0.0 F19 Mean 1.22 2.623 0.0 1.674 0.0 2.623 SD 1.22 0.01.674 0.0 F20 947.823 372.07 411.16 394.573 362.217 Mean 947.823 SD 372.07 411.16 394.573 362.217 F21 -2985.634 -2835.156 -2129.06 -3076.838 -2928.403 Mean SD 2835.156 2985.634 2129.06 3076.838 2928.403 F22 8.894 Mean 4.574 6.747 8.116 2.80 SD 4.574 8.894 2 6.747 8.116 2.80 F23 2.175 Mean 0.330 1.592 0.054 0.398 2.175 SD 1.592 0.054 0.330 0.398 F24 7.155 Mean 2.086 2.938 0.448 1.976 2.086 7.155 2.938 0.448 1.976 SD

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TABLE 8 Mean and standard deviation (SD) of the errors of HS variants for (D = 50).							
F	Index	Algorithms		×	,		
		EHS2011	IGHS 2013	DHBest 2016	HS-SA 2018	GWO-HS	
F1	Mean	3.958 e-6	382.791	0.0	524.218	0.0	
	SD	3.958 e-6	382.791	0.0	524.218	0.0	
F2	Mean	2.08 e-5	8.310	0.0	10.119	0.0	
	SD	2.08 e-5	8.310	0.0	10.119	0.0	
F3	Mean	0.0	280	0.0	535.9	0.0	
	SD	0.0	280	0.0	535.9	0.0	
F4	Mean	48.869	18234	48.644	30394	47.718	
	SD	48.869	18234	48.644	30394	47.718	
F5	Mean	-12372.787	-20216	-20929	-20093	-20750	
	SD	12372.787	20216	20929	20093	20750	
F6	Mean	2.677	41.536	1.519	45.022	0.0	
	SD	2.677	41.536	1.519	45.022	0.0	
F7	Mean	1.678 e-4	4.366	4.440 e-16	5.711	4.440 e-16	
	SD	1.678 e-4	4.366	4.440 e-16	5.711	4.440 e-16	
F8	Mean	0.054	2.476	0.0	5.788	0.0	
	SD	0.054	2.476	0.0	5.788	0.0	
F9	Mean	54.862	4507.177	0.0	8509	0.0	
	SD	54.862	4507.177	0.0	8509	0.0	
F10	Mean	0.057	0.471	0.306	0.488	0.037	
	SD	0.057	0.471	0.306	0.488	0.037	
F11	Mean	3.165	7410.696	175.885	131.789	0.036	
	SD	3.165	7410.696	175 885	131.789	0.036	
F12	Mean	0.103	1.08	0.051	2.329	2.528 e-68	
	SD	0.103	1.08	0.051	2.329	2.528 e-68	
F13	Mean	-42.985	-45.301	-45.144	-45.094	-45.370	
	SD	42.985	45.301	45.144	45.094	45.370	
F14	Mean	0.724	270.194	25.759	360.223	0.666	
	SD	0.724	270.194	25.759	360.223	0.666	
F15	Mean	0.195	17.166	0.169	23.059	0.0	
	SD	0.195	17.166	0.169	23.059	0.0	
F16	Mean	2.50 e-9	3.774 e-12	2.799 e-7	6.07 E-13	7.591 e-19	
	SD	2.50 e-9	3.774 e-12	2.799 e-7	6.07 E-13	7.591 e-19	
F17	Mean	3.319	7.999	1.813	1.729	2.954	
	SD	3.319	7.999	1.813	1.729	2.954	
F18	Mean	0.129	7.635	0.0	5.176	0.0	
	SD	0.129	7.635	0.0	5.176	0.0	
F19	Mean	3.835	5.289	0.0	4.437	0.0	
	SD	3.835	5.289	0.0	4.437	0.0	
F20	Mean	1051.242	682667.321	1096.557	4199.406	1032.046	
	SD	1051.242	682667.321	1096.557	4199.406	1032.046	
F21	Mean	-4094.937	4539.074	-4936.221	-4894.840	-4399.1614	
	SD	4094.937	4539.074	4936.221	4894.840	4399.1614	
F22	Mean	11.247	23.853	12.479	21.414	8.30	
	SD	11.247	23.8532	12.479	21.414	8.30	
F23	Mean	0.527	25.025	0.652	2.710	0.579	
	SD	0.527	25.025	0.652	2.710	0.579	
F24	Mean	4.004	173.633	3.528	22.184	3.887	
	SD	4.004	173.633	3.528	22.184	3.887	

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TABLE 9 MEAN AND STANDARD DEVIATION (SD) OF THE ERRORS FOR THE EXISTING OPTIMIZATION ALGORITHMS FOR (D = 30). Index F Algorithms ACS 2013 Multiverse 2016 ABC2005 DE 1997 **GWO-HS** Mean 0.0039 173.066 3.356 e-34 1.674 F1 0.0 SD 3.356 e-34 0.0039 1.674 173.066 0.0 F2 Mean 5.936 e-20 0.024 0.158 0.623 0.0 SD 5.936 e-20 0.024 0.158 0.623 0.0 F3 0.0 0.0 0.666 775.266 Mean 0.0 SD 0.0 0.666 0.0 775.266 0.0 F4 Mean 33.133 28.816 2232289.712 161316.322 27.766 SD 33.133 28.816 2232289.712 161316.322 27.766 F5 -12542.508 -6745.606 -11701.463 -10417.237 -12540.709 Mean 12542.508 6745.606 11701.463 12540.709 SD 10417.237 F6 0.8622 2.026 7.07 44.736 Mean 0.0 SD 0.8622 7.07 2.026 44.736 0.0 F7 Mean 0.098 0.051 2.545 6.379 4.440 e-16 SD 0.098 0.051 2.545 6.379 4.440 e-16 F8 Mean 0.001 0.009 0.348 3.338 0.0 SD 0.001 0.009 0.348 3.338 0.0 F9 8.252 e-34 0.582 0.0 2137.225 Mean 0.0 SD 8.252 e-34 0.582 0.0 2137.225 0.0 F10 Mean 0.195 0.009 0.459 0.347 0.009 SD 0.009 0.459 0.195 0.347 0.009 F11 Mean 0.871 0.001 335.010 4.624 1.002 e-5 SD 0.871 0.001 335.010 4.624 1.002 e-5 F12 1.221 e-6 0.017 0.014 0.567 Mean 1.153 e-62 SD 1.221 e-6 0.017 0.014 0.567 1.153 e-62 F13 Mean -26.864 -26.850 -26.553 -26.833 -26.753 SD 26.864 26.850 26.553 26.833 26.753 F14 0.746 0.741 3366.446 1036.294 Mean 0.666 SD 0.746 0.741 3366.446 1036.294 0.666 F15 1.186 e-36 0.001 0.230 6.354 Mean 0.0 SD 1.186 e-36 0.001 0.230 6.354 0.0 F16 2.913 e-148 9.550 e-12 1.131 e-16 1.439 e-4 Mean 0.0 SD 2.913 e-148 9.550 e-12 1.131 e-16 1.439 e-4 0.0 F17 Mean 3.349 3.349 3.349 3.349 0.305 SD 3.349 3.349 3.349 3.349 0.305 F18 Mean 0.0 0.0 0.0 0.0 0.0 SD 0.0 0.0 0.00.0 0.0 F19 0.0 Mean 0.0 3.250 e-10 0.00.0 SD 3.250 e-10 0.0 0.00.0 0.0 F20 413.952 413.952 413.952 413.952 Mean 362.217 SD 413.952 413.952 413.952 413.952 362.217 F21 Mean -3099.99 -2971.234 -3088.953 -3075.226 -2928.403 SD 3099.99 2971.234 3088.953 3075.226 -2928.403 7.013 3.324 Mean 13.676 17.238 F22 2.80 SD 7.013 3.324 2 13.676 17.238 2.80 1.668 F23 Mean 1.668 1.668 1.668 0.398 SD 1.668 1.668 1.668 1.668 0.398 F24 3.0 3.0 3.0 3.0 Mean 1.976 SD 3.0 3.0 3.0 3.0 1.976

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TABLE 10 MEAN AND STANDARD DEVIATION (SD) OF THE ERRORS EXISTING OPTIMIZATION ALGORITHMS FOR (D = 50). F Index Algorithms ACS 2013 **GWO-HS** Multiverse 2016 ABC2005 DE 1997 F1 Mean 5.212 e-19 0.027 1689.224 459.970 0.0 0.027 1689.224 459.970 SD 5.212 e-19 0.0 F2 5.496 e-12 0.065 6.481 1.352 0.0 Mean SD5.496 e-12 0.065 6.481 1.352 0.0 F3 0.0 Mean 1.4 1.633 0.3 2854.266 SD 1.4 1.633 0.3 2854.266 0.0 F4 47.718 96.360 50.836 2050687.392 2232815.458 Mean SD 96.360 50.836 2050687.392 2232815.458 47.718 F5 -20750.237 Mean -20842.549 -10662.148 -17807.783 -16560.174 20750.237 SD 20842.549 10662.148 17807.783 16560.174 F6 Mean 4.123 5.1942 50.508 95.855 0.0 95.855 SD 4.123 5.1942 50.508 0.0 F7 Mean 0.271 0.097 9.991 9.743 4.440 e-16 4.440 e-16 9.743 SD 0.271 0.097 9.991 F8 0.004 0.057 13.013 10.318 0.0 Mean SD 0.004 0.057 13.013 10.318 0.0 F9 3.679 e-18 18.199 26232.197 14722.357 0.0 Mean SD 3.679 e-18 18.199 26232.197 14722.357 0.0 F10 0.384 0.042 0.497 0.477 0.037 Mean 0.477 SD 0.384 0.042 0.497 0.037 F11 Mean 24.058 0.034 667.084 144.123 0.036 SD 24.058 0.034 667.084 144.123 0.036 F12 1.573 e-4 0.114 0.619 1.804 2.528 e-68 Mean 2.528 e-68 1.804 SD 1.573 e-4 0.114 0.619 F13 -45.370 -45.283 Mean -45.313 -45.385 -44.409 45.370 SD 45.313 45.385 44.409 45.283 F14 Mean 3.910 1.022 43610.849 23618.905 0.666 23618.905 SD 3.910 1.022 43610.849 0.666 F15 0.016 41.068 0.0 7.768 e-21 88.173 Mean SD 7.768 e-21 0.016 88.173 41.068 0.0 F16 2.123 e-124 7.591 e-19 6.993 e-12 Mean 8.463 e-5 2.128 e-4 SD 2.123 e-124 6.993 e-12 8.463 e-5 2.128 e-4 7.591 e-19 F17 5.166 5.166 5.166 2.954 Mean 5.166 SD 5.166 5.166 5.166 5.166 2.954 F18 0.0 0.0 0.0 0.0 0.0 Mean 0.0 SD 0.0 0.0 0.0 0.0 F19 Mean 0.0 0.0 0.0 0.0 0.0 SD 0.0 0.0 0.0 0.0 0.0 F20 Mean 1149.869 1149.869 1149.869 1149.869 1032.046 SD 1149.869 1149.869 1149.869 1149.869 1032.046 F21 -4682.634 -4891.577 -4399.161 Mean -5099.996 -5011.839 SD 5099.996 4682.634 4891.5774 5011.839 4399.161 F22 15.965 9.513 34.917 31.775 8.30 Mean 8.30 SD15.965 9.513 34.917 31.775 F23 Mean 1.472 1.472 1.472 1.472 0.579 SD1.472 1.472 1.472 1.472 0.579 F24 Mean 5.0 5.0 5.0 5.0 3.887 SD 5.0 5.0 5.0 5.0 3.887



TABLE 11 MEAN AND STANDARD DEVIATION (SD) OF THE ERRORS FOR HS VARIANTS USING THE CEC2014 (D = 30). F Index Algorithms EHS2011 DHBest 2016 HS-SA 2018 **GWO-HS IGHS 2013** F1 Mean 4.78 E7 2.44 E7 2.17 E7 1.64 E7 413113 2.44 E7 4.78 E7 413113 SD 2.17 E7 1.64 E7 35 36 Time 402.25 32.483 60.163 F2 1.016 E9 2799924 Mean 1.62 E8 1180792 18904 1.016 E9 2799924 18904 SD 1.62 E8 1180792 Time 20 18 219.85 17.855 20.395 F3 9247 12394 5051 15863.40 13003 Mean 12394 9247 SD 15863.40 13003 5051 21 20 Time 239.87 20.542 25.632 F4 644 533 Mean 530.31 439 538 533 644 SD 530.31 538 439 21 20.45 256.36 Time 25.033 20.926 F5 520.67 519.99 520.08 520.00 Mean 520.04 520.67 519.99 520.08 520.00 SD 520.04 33.023 405.066 49.116 Time 31.048 32.749 F6 619.58 616.68 Mean 614.96 616 620.245 SD 619.58 616.68 614.96 616 620.245 3305 3499.66 39014 Time 4057.221 6312.374 F7 708.46 700.95 708.03 Mean 700.52 700.01 708.46 700.95 708.03 SD 700.52 700.01 41 485 Time 40.83 41.882 52.229 F8 Mean 863.71 800.20 803.37 800.09 800 863.71 800.20 803.37 SD 800.09 800 29 335 Time 27.35 27.826 27.31 F9 1047.49 977.72 989.04 971.87 1037 Mean 1047.49 989.04 977.72 SD 971.87 1037 38.59 Time 36 460 39.245 37.85 F10 1995.28 1048.71 Mean 1001.11 1001.26 1001 1995.28 1048.71 1001.11 1001.26 1001 SD 58 13273 56.51 60.757 63.43 Time F11 4479.43 3333.98 3282.25 3793.02 Mean 3220.57 4479.43 SD 3333.98 3282.25 3220.57 3793.02 67 82.37 726.23 97.10 Time 69.857 F12 1200.71 1200.17 Mean 1200.16 1200.22 1200.18 1200.71 1200.17 SD 1200.16 1200.22 1200.18 690 708.27 8221 739.323 1083.54 Time F13 1300.62 1300.55 1300.64 Mean 1300.57 1300.59 1300.64 1300.62 1300.55 SD 1300.57 1300.59 28 360.72 17.811 Time 26.45 26.858 F14 1686.38 1660.91 Mean 1686.04 1685.41 1685.40 1686.38 1660.91 SD 1686.04 1685.40 1685.41 29 26.40370 Time 26.07 16.18 F15 1541.48 1519.03 2321.51 1515.24 Mean 1537.52 1541.48 SD 1519.03 2321.51 1515.24 1537.52 43 492 41.091 Time 40.17 32.40 F16 1610.12 1610.07 1610.51 1611.25 1610.06 Mean 1610.07 1610.12 1610.51 1611.25 SD 1610.06 497 41.409 31.95 Time 42 39.22 2699841 2894964 F17 3011342 3716289.87 58210.62 Mean 2699841 3011342 2894964 3716289.87 SD 58210.62 Time 52 51.86 639 54.856 24.30 F18 7058.42 445339 3523.70 Mean 12719 5989.24

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SD 12719 7058.42 445339 5989.24 3523.70 Time 37 34.15 437 37.037 24.30 F19 2539.23 2296.31 2534 2538.38 2539 Mean 2296.31 SD 2539.23 2534 2538.38 2539 Time 834 798.49 9895 947.406 1046 F20 15049.83 Mean 14549.12 15983.76 28188 17269.85 15049.83 SD 14549.12 15983.76 28188 17269.85 Time 37 36.81 448 30.658 49.09 F21 Mean 748419 585489 1097997 774049.91 61828 SD 748419 585489 1097997 774049.91 61828 Time 49 47.32 856 40.798 63 F22 2758 2844 2703.86 2813 Mean 2727.08 SD 2758 2727.08 2844 2703.86 2813 139.4 Time 115 114.450 1696 109.921 F23 Mean 2616.48 2620.21 2616.43 2500 2617 SD2617 2616.48 2620.21 2616.43 2500 Time 1976 134.524 173.45 139 139.79 F24 2603 2600 Mean 2600 2635.87 2634.43 SD 2600 2635.87 2603 2634.43 2600 Time 1503 127.97 107 111.17 118.136 F25 Mean 2707 2710.26 2700.32 2709.29 2700 SD 2707 2710.26 2700.32 2700 2709.29 Time 140 142.09 1846 155.969 172.26 F26 Mean 2782 2740.74 2800.04 2766.17 2798.04 SD 2782 2740.74 2800.04 2798.04 2766.17 Time 4118 4186.60 50167 3616.477 11220.31 F27 2900 Mean 3443 3431.52 3273.93 3401.17 SD 2900 3443 3431.52 3273.93 3401.17 Time 4382 4398 45428 2723.65 5419.98 F28 Mean 4495 3925.84 4050.87 3870.42 3000 SD4495 3925.84 4050.87 3870.42 3000 Time 299 186.109 344.37 295.402768 F29 3100 Mean 16215 4177.09 2015087 4362.35 SD16215 4177.09 2015087 4362.35 3100 Time 926 825 9245 1190.62 646.452 F30 Mean 14983 11741.60.0 17050.01 11977.69 3200 14983 SD 17050.01 11977.69 3200 11741.60 208 178.75 126.545 369.84 Time 1773

TABLE 12

MEAN AND STANDARD DEVIATION (SD	OF THE ERRORS EXISTING OPTIMIZATION ALGORITHMS USING THE CEC2014 (D	0 = 30).
THE BUILT DE FILLED DE FILLED (~~	of the Endorable Contrainer the of the contrainer of the contrainer (b	

F	Index	Algorithms				
		ACS 2013	MultiVerse 2016	ABC2005	DE 1997	GWO-HS
F1	Mean	68849	2463618	2.34 E7	3889379	413113
	SD	68849	2463618	2.34 E7	3889379	413113
	Time	273	174	113	449	60.163
F2	Mean	200	1908	993	4.76 E8	18904
	SD	200	1908	993	4.76 E8	18904
	Time	147	97	32	163	20.395
F3	Mean	300	374	1600.05	5684	5051
	SD	300	374	1600.05	5684	5051
	Time	161	95	38	197	25.632
F4	Mean	400.42	470	500.03	512	439
	SD	400.42	470	500.03	512	439
	Time	172	99	43	198	25.033
F5	Mean	520.01	520	520.01	520.81	520.00
	SD	520.01	520	520.01	520.81	520.00

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49.116



Time

228

139 89 389 F6 Mean 610.23 604.01 613 620.245 617.59 SD 610.23 604.01 617.59 620.245 613 37222 Time 16555 17323 84542 6312.374 700 F7 Mean 700.01 700.11 706.74 700.01 SD 700 700.01 700.11 706.74 700.01 Time 235 207 110 451 52.229 F8 800.91 Mean 800 868 856.48 800 SD 800.91 800 868 800 856.48 Time 162 165 12749 856.48 27.31 F9 Mean 961 971 1039.01 993 1037 SD961 971 1039.01 993 1037 Time 231 192 85 527 37.85 F10 Mean 1000.49 2649.50 1000.08 1743 1001 SD 1000.49 2649.50 1000.08 1743 1001 Time 337 63.43 316 158 881 F11 Mean 2899.09 3793.02 4168.99 3536.66 6115 SD 2899.09 4168.99 3793.02 3536.66 6115 Time 423 360 221 1103 97.10 F12 Mean 1200.10 1200.16 1200.14 1201.50 1200.18 SD 1200.10 1200.16 1200.14 1201.50 1200.18 Time 4105 3451 3011 11534 1083.54 F13 Mean 1300.29 1300.22 1300.55 1300.26 1300.40 SD 1300.29 1300.22 1300.55 1300.26 1300.40 Time 160 17.811 167 56 215 F14 Mean 1685.39 1691 1685.39 1686.15 1685.40 SD 1685.39 1691 1685.39 1686.15 1685.40 Time 169 227 169 67 16.18 F15 1505.86 Mean 1508.67 1516.61 1537.52 1612.67 SD 1505.86 1508.67 1516.61 1612.67 1537.52 Time 243 216 116 476 32.40 F16 Mean 1610.51 1609.12 1610.97 1610.11 1611.78 SD 1609.12 1610.51 1610.97 1610.11 1611.78 Time 31.95 247 218 127 497 F17 Mean 15909.63 68155 440195.74 58210.62 3051313 SD 15909.63 68155 440195.74 58210.62 3051313 Time 348 267 701 24.30 203 F18 Mean 1970.31 3693 7320 3.09 E7 3523.70 SD 1970.31 3693 7320 3.09 E7 3523.70 Time 277 24.30 205 112 406 F19 Mean 2538.04 2547.94 2539 2538.38 2538.97 SD 2538.04 2547.94 2538.38 2539 2538.97 Time 6847 3787 3944 14593 1046 F20 Mean 2799 2227 15049.83 22185.48 5931 SD 2799 2227 15049.83 22185.48 5931 Time 246 221 118 434 49.09 F21 7125.01 Mean 34062 658713 125970 61828 SD 7125.01 34062 658713 125970 61828 Time 314 160 63 275 593 F22 Mean 2550.16 2475.32 2486 2813 2657.33 SD 2475.32 2813 2657.33 2486 2550.16 Time 139.4 503 1809 611 721 F23 Mean 2615.24 2502 2617.83 2617.13 2500 SD 2615.24 2502 2617.83 2617.13 2500 Time 999 715 662 2406 173.45 F24 Mean 2627 2600.60 2630 2646.36 2600 SD 2627 2600.60 2630 2600 2646.36



	Time	781	703	500	1761	127.97
F25	Mean	2707.99	2700.08	2712	2711.38	2700
	SD	2707.99	2700.08	2712	2711.38	2700
	Time	1059	919	633	2227	172.26
F26	Mean	2715	2700.34	2721	2725.87	2798.04
	SD	2715	2700.34	2721	2725.87	2798.04
	Time	26476	21762	21399	61044	11220.31
F27	Mean	3124	2903.90	3168	3297.27	2900
	SD	3124	2903.90	3168	3297.27	2900
	Time	25270	21615	20556	48621	5419.98
F28	Mean	3753	3017.05	4751	3913.60	3000
	SD	3753	3017.05	4751	3913.60	3000
	Time	1776	1831	1339	2895	344.37
F29	Mean	3626.38	19816.49	4931	59318.770	3100
	SD	3626.38	19816.49	4931	59318.770	3100
	Time	6063	4775	4515	9249	1190.62
F30	Mean	5500.63	5142.61	7907	7762.58	3200
	SD	5500.63	5142.61	7907	7762.58	3200
	Time	1403	1232	916	1876	369.84

TABLE 13

WILCOXON SIGNED-RANK TEST RESULTS GWO-HS VS HS VARIANTS 30D.					
Algorithms	P-value	R+	R-	n/h/l/s	
GWO-HS vs EHS2011	0.0001	221	-52	24/21/1/2	
GWO-HS vs IGHS 2013	0.00022	276	0	24/24/0/0	
GWO-HS vs DHBest 2016	0.00782	217	-23	24/14/2/8	
GWO-HS vs HS-SA 2018	0.00614	254	-22	24/21/3/0	

TABLE 14

WILCOXON SIGNED-RANK TEST RESULTS GWO-HS VS HS VARIANTS 50D.					
P-value	R+	R-	n/h/l/s		
0.0001	208	-2	24/20/3/1		
0.0001	251	-21	24/22/2/0		
0. 02642	188	-29	24/13/3/8		
0.0002	247	-6	24/21/3/0		
	WILCOXON SIGNED-1 P-value 0.0001 0.0001 0.02642 0.0002	WILCOXON SIGNED-RANK TEST RESULTS GWO-HS V P-value R+ 0.0001 208 0.0001 251 0.02642 188 0.0002 247	WILCOXON SIGNED-RANK TEST RESULTS GWO-HS VS HS VARIANTS 50D. P-value R+ R- 0.0001 208 -2 0.0001 251 -21 0.02642 188 -29 0.0002 247 -6		

TABLE 15

W	ILCOXON SIGNED-RANK	CTEST RESULTS GWO-HS VS OTH	ER METAHEURISTICS 50D.	
Algorithms	P-value	R+	R-	n/h/l/s
GWO-HS vs ACS 2013	0. 00374	225	0	24/21/0/3
GWO-HS vs MultiVerse 2016	0.00124	228	0	24/22/0/2
GWO-HS vs ABC2005	0. 00078	213	-8	24/19/1/4
GWO-HS vs DE 1997	0. 00044	228	0	24/22/0/2

XON SIGNED-RANK TE	TABLE 16 ST RESULTS GWO-HS VS OTHER	R METAHEURISTICS 50D.	
value F	{ +	R-	n/h/l/s
00214 2	231	-15	24/20/2/2
00086 2	240	-4	24/21/1/2
00034 2	249	-8	24/20/2/2
00038 2	256	-4	24/20/2/2
	KON SIGNED-RANK TE alue F 00214 2 00086 2 00034 2 00038 2	TABLE 16 CON SIGNED-RANK TEST RESULTS GWO-HS VS OTHER alue R+ 00214 231 00086 240 00034 249 00038 256	TABLE 16 TABLE 16 CON SIGNED-RANK TEST RESULTS GWO-HS VS OTHER METAHEURISTICS 50D. alue R+ R- 00214 231 -15 00086 240 -4 00034 249 -8 00038 256 -4

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		IABLE	1/		
	WILCOXON SIGNED	-RANK TEST RESULTS GW	VO-HS VS HS VARIANTS CEC2014 3	30D.	
	P-value	R+	R-	n/h/l/s	
GWO-HS vs EHS2011	0.0002	414	-50	30/25/4/1	
GWO-HS vs IGHS 2013	0.01778	347	-117	30/19/-11/0	
GWO-HS vs DHBest 2016	0.00044	403	-62	30/24/6/0	
GWO-HS vs HS-SA 2018	0.00782	359	-103	30/22/8/0	

WILCO	KON SIGNED-RANK	TAB TEST RESULTS GWO	LE 18 -hs vs other metaheuristics CEC 20	014 30d.
Algorithms	P-value	R+	R-	n/h/l/s
GWO-HS vs ACS 2013	0. 03662	362	-103	30/22/8/0
GWO-HS vs Multiverse 2016	0. 4965	267	-195	30/17/11/2
GWO-HS vs ABC2005	0. 14706	300	-163	30/16/13/1
GWO-HS vs DE 1997	0.00128	389	-76	30/23/7/0







FIGURE 3. CONVERGENCE CURVE FOR F4

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FIGURE 4. CONVERGENCE CURVE FOR F6

FIGURE 5. CONVERGENCE CURVE FOR	r f7
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TABLE 19						
FRIEDMAN TEST RESULTS GWO-HS VS HS VARIANTS.						
Algorithms	Classical 30D	Classical 50D	CEC2014 30D			
EHS2011	2.8542	2.9583	4.0833			
IGHS 2013	4.1250	4.2083	2.6333			
DHBest 2016	2.9792	2.1875	3.6000			
HS-SA 2018	3.3750	4.1667	2.7000			
GWO-HS	1.6667	1.4792	1.9833			
	FRIEDMAN TEST RESULTS GW	D-HS VS OTHER METAHE	URISTICS.			
Algorithms	Classical 30D	Classical 50D	CEC2014 30D			
ACS 2013	2.4792	2.5417	1.8667			
Multiverse 2016	3.1458	2.8750	2.6667			
ABC2005	3.6250	2.5417	3.4500			
DE1997	4.1875	3.9583	4.2333			
GWO-HS	1.5625	1.5000	2.7833			

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Table 4 shows that the best results for the hybrid algorithm are obtained using HMS = 5 and shows the fastest results obtained in most functions. Table 4 shows that increasing HMS does not improve the performance in most algorithms. Thus, a small HMS improves the update rate in HM for most cases. Table 5 presents the results of running the hybrid algorithm with different HMCR values (i.e., 0.7, 0.8, 0.9, and 0.99). The obtained results show that the HMCR value has a high influence on the HS performance. A large HMCR value provides improved results. The best results are obtained using HMCR = 0.99 for most benchmark functions with the fastest convergence rate. Through the experiment of HMS values, we use HMCR = 0.99 and HMS = 5 to run the HMCR value experiment.

B. EXPERIMENT 1

In this part, we will analyze the experiment of the new hybrid algorithm compared with four recent HS variants and one hybrid algorithm (i.e., EHS 2011, IGHS 2013, DH/best 2016 and HS-SA 2018). The parameter configurations for these variants are described in Table 4. The parameter values for the hybrid algorithm are the same as those listed in Table 2. First, we examine the hybrid algorithm together with four HS variants using 24 benchmark functions with 30 and 50 dimensions, as described in Table 1.

For both dimensions, as presented in Tables 7 and 8, the hybrid algorithm provides better results than the other HS variants in most cases. Second, we compare the hybrid algorithm with the recent variants of HS using 30 state-of-the-art CEC benchmark functions [45], with 30 dimensions. The results presented in Table 11 show that the new hybrid algorithm outperforms the recent variants in 20 out of the 30 test cases and provides highly competitive results. In terms of speed, the algorithm only outperforms the other variants in seven functions, but it provides high speed in all cases.

Wilcoxon's rank test was applied to the mean results of Tables 7, 8, and 11 presented in Tables 13, 14, and 17 respectively. The p-value shows the significance of the results and performance improvement in comparison with other variants. A low p-value means high improvement. R+ presents the total ranks whenever the hybrid algorithm provides better results than the other variants, whereas R- provides the total ranks of lower results than the other variants. N is the total number of benchmark functions, l, h, and s indicate the total number of functions with higher, lower, or similar results of the hybrid algorithm compared with other variants. As presented in Tables 13, 14, and 17, the new hybrid algorithm outperforms all variants of HS with improved performance. Finally, to establish a comparative assessment, Friedman statistical test has been conducted based on the mean results of Tables 7, 8, and 11. The results presented in Table 19 confirm that the new hybrid algorithm outperforms all previous variants of HS because it provides the highest ranking. These results obtained the lowest value on the Friedman test, which shows a high ranking. The results contain classical 30D as classical benchmark functions with 30 dimensions, and classical 50D as classical benchmark functions with 50 dimensions, and finally the CEC2014 test cases with 30 dimensions.

C. EXPERIMENT 2

To investigate the capability of the hybrid algorithm, we evaluate it with other state-of-the-art metaheuristic algorithms from different families, as follows: artificial cooperative search (ACS 2013) [46], (multi-verse 2016) [47], artificial bee colony (ABC 2005)[48], and differential evolution (DE 1997) [49]. The parameter characteristics of these algorithms are shown in Table 3 as used in this experiment.

In Table 9, we compare the hybrid algorithm with other metaheuristics using classical benchmark functions as described in Table 1. These functions have 30 dimensions. The hybrid algorithm provides the best results in all test functions, except for F5 and F13. The hybrid algorithm provides the second-best results. Table 10 presents the mean, and the SD of the hybrid algorithm with other metaheuristics by using 50 dimensions for the classical benchmark functions. The hybrid algorithm outperforms other metaheuristics in all test functions, except for F5, F13, and F16; the hybrid algorithm provides the second-best result. Finally, we compare the hybrid algorithm with other metaheuristics in Table 12 using 30 state-of-the-art benchmark functions from CEC 2014. The results of mean and standard deviations and running time show that the hybrid algorithm provides the highest speed in all the 30 cases. Moreover, this algorithm outperforms all other metaheuristics in 12 cases, as presented in Table 12. Overall, according to the results shown in Tables 9 and 10, the hybrid algorithm provides a competitive result compared to other metaheuristic algorithms in terms of efficiency.

Similar to the previous section, we conducted Wilcoxon's rank test and Friedman statistical test based on the mean results of Tables 9, 10, and 12. The Wilcoxon's rank test results presented in Tables 15, 16, and 18 were derived from 30, 50 dimensions of classical benchmark functions, and CEC2014 test cases, respectively.

As shown in Tables 15 and 16, the hybrid algorithm provides very small p-values. Therefore, it outperforms all other metaheuristic algorithms and provides very high significant improvement. Table 18 shows the results based on CEC2014 experiment results presented in Table 12. The hybrid algorithm provides high significance results against two algorithms, namely, ACS and DE.

For the Friedman test, Table 20 presents a full overview of the classical benchmark functions with two dimensions, 30 and 50, and the CEC test cases. As seen in the classical experiments, the hybrid algorithm has the lowest value on Friedman test, which means it has the highest ranking among other metaheuristics. For the CEC2014 experiment, the hybrid algorithm has the second raking following ACS algorithm.

To provide insight into the hybrid algorithm convergence rate, we run experiment using four benchmark functions. Two functions with unimodal optimum (F1, F4), and two functions with multimodal optimum (F6, F7). Figures (2 - 5) illustrate the best score obtained so far of the hybrid algorithm and other HS variants versus the iteration.

VII. CONCLUSION

This paper presents a new hybrid algorithm of the HS algorithm with the GWO algorithm called GWO-HS algorithm for the global continuous optimization problem. The 20

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new hybrid algorithm solves the parameter selection problem of the HS algorithm by using another algorithm, namely, GWO, to modify the values of the PAR and BW parameters as a self-adaptive process. Another modification is performed to harmonize search by applying the modified opposition technique to the search result and improving the obtained results. The GWO-HS convergence is very high compared to the existing HS variants due to the opposition technique, and GWO-HS can reach the optimum results with less iterations. The new hybrid algorithm can cover different types of problems with the same parameter setting, which makes it a better version of HS than the original one. Two groups of evaluation tests are used to examine the new algorithm performance. First, we compare the hybrid algorithm with the recent variants of the HS algorithm using different types of optimization functions, namely, 24 classical and 30 CEC2014 benchmark functions. The results show that the hybrid algorithm is better than the previous variants in terms of accuracy and provides competitive time consumption. Additionally, the algorithm has been evaluated with wellknown metaheuristics from different families. The hybrid algorithm shows improved results and speed compared with these algorithms. The new hybrid algorithm shows high performance, which is essential in solving real-world optimization. Therefore, we recommend using a new algorithm to solve real-world problems. The current experiment focuses on continuous benchmark functions. Future work could utilize the new hybrid algorithm in discrete optimization problems.

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