

HUNGER BEHAVIOUR CLASSIFICATION OF
LATES CALCARIFER USING MACHINE
LEARNING FOR AUTOMATIC
DEMAND FEEDER THROUGH
IMAGE PROCESSING

MOHD AZRAAI BIN MOHD RAZMAN

DOCTOR OF PHILOSOPHY

UNIVERSITI MALAYSIA PAHANG



SUPERVISOR'S DECLARATION

I hereby declare that I have checked this thesis and in my opinion, this thesis is adequate in terms of scope and quality for the award of the degree of Doctor of Philosophy.

(Supervisor's Signature)

Full Name : DR. AHMAD SHAHRIZAN BIN ABDUL GHANI

Position : SENIOR LECTURER

Date : 7TH NOVEMBER 2019



STUDENT'S DECLARATION

I hereby declare that the work in this thesis is based on my original work except for quotations and citations which have been duly acknowledged. I also declare that it has not been previously or concurrently submitted for any other degree at Universiti Malaysia Pahang or any other institutions.

(Student's Signature)

Full Name : MOHD AZRAAI BIN MOHD RAZMAN

ID Number : PFM17001

Date : 7TH NOVEMBER 2019

HUNGER BEHAVIOUR CLASSIFICATION OF LATES CALCARIFER USING
MACHINE LEARNING FOR AUTOMATIC DEMAND FEEDER THROUGH
IMAGE PROCESSING

MOHD AZRAAI BIN MOHD RAZMAN

Thesis submitted in fulfillment of the requirements
for the award of the degree of
Doctor of Philosophy

Faculty of Manufacturing & Mechatronic Engineering Technology
UNIVERSITI MALAYSIA PAHANG

NOVEMBER 2019

ACKNOWLEDGEMENTS

Wallahi, it has been a remarkable journey, blessed by Him, with the support from family and friends. Firstly to my wife, Nurjalilah Md. Yatim, thank you for being by my side throughout the odyssey in completing my studies. Your resilience and trust were the pivotal constituents in keeping me on track. Our son, Muhammad Asif adores us as he has been the optimistic factor for engaging us uniformly. To my parents and in-laws, especially to ‘mama’ Pn. Aida and siblings (Azhar, Azmil, Azam, Azri and Azra), thank you for the unity.

If it were not for Prof. Dr. Zahari Taha, the realisation in accomplishing this thesis would be tenuous. I will still remember the four key factors; research, teaching, administration and consultation that he has advised me on the route in becoming a great academician. The conducive environment he founded, IMAMS laboratory, where some of us consider it as a second home (literally at times), has boosted the conceptual provision of working in the academic world.

The collaboration made with Dr. Mukai and his lab members at IIUM Kuantan has opened a lot of doors in grasping the interdisciplinary field as it seems to be the genesis of propagating quality research. Dr. Shahrizan has been supportive in ensuring that the thesis reaches prominent standards.

To Dr. Gian-Antonio Susto and Prof. Dr. Angelo Cenedese, honestly my ‘crusade’ so I call during visiting PhD at the University of Padova, Italy was one of the monumental durations where I have to battle with the utmost quality in achieving substantial results. They are forever my guru in Machine Learning.

Dr. Anwar and Dr. Rabiu, these two main characters have charted the avenue in concluding my research and thesis. The awareness that they have brought and moments where ‘punishing’ is required was inevitable, and for that, I am very grateful. To Mr. Faeiz Azizi and Mr. Jessnor, they involved in the development of the device, their expertise has led to comprehensive findings in this thesis, and it was a delight to be working with them.

There are numbers of people contributed and supported me, and I would love to list them all but forgive me, whoever you are you know I would if I could. The members in IMAMS Lab, the fun and joy that we had has somewhat provided the extra nudge for me. The unity has brought us to where we are. Coming together is a beginning; keeping together is progress; working together is a success.

Lastly, to share the serenading Italian words (pardon for the explicit content) that keep repeating in the streets of Padova, considerably had a major impact on me as motivation in completing my PhD.

Dottore! dottore!

Dottore del buco del culo

Vaffanculo! Vaffanculo!

ABSTRAK

Pemahaman dan pengecaman kelakuan ikan ketika lapar merupakan kunci dalam peningkatan produk akuakultur. Oleh itu, tesis ini mensasarkan kepada pengelasan ikan siakap (*Lates Calcarifer*) ketika lapar menggunakan teknik integrasi pemprosesan imej dan pembelajaran mesin. Teknik kluster min-k digunakan untuk menentukan jumlah kelas yang relevan daripada data mentah. Hasil teknik kluster min-k ini, dua kelas, “Lapar” dan “kenyang”, telah ditentukan sebagai relevan untuk penyelidikan ini berdasarkan ciri-ciri tertentu yang ditunjukkan ketika ikan-ikan tersebut lapar dan kenyang. Ciri-ciri tersebut dianalisis melalui analisis plot kotak, dan Analisis Komponen Utama (PCA). Ciri yang telah dipastikan adalah COG x, COG y, dan penjumlahan pergerakan piksel. Pelbagai model pembelajaran mesin seperti Analisis Diskriminan (DA), Mesin Vektor Sokongan (SVM), k -Jiran Terdekat (k -NN) telah digunakan untuk menentukan model terbaik untuk membuat pengelasan keadaan ikan tersebut. Teknik SVM mampu memberikan pengelasan terbaik sehingga 99.00%. Penyelidik percaya teknik ini sesuai untuk digunakan dalam bidang penternakan ikan. Analisis tambahan dilakukan untuk memahami ritma sirkadian ikan dengan menilai ciri masa-bersiri. Pelbagai saiz tetingkap daripada 0.5 minit, 1.0 minit, 1.5 minit and 2.0 minit telah diselidiki bersama min, maksimum, minimum dan varian untuk setiap tempoh masa tersebut. PCA dan PCA pusingan varimax telah digunakan untuk menentukan ciri terbaik untuk pengelasan melalui SVM dan k -NN. Hasil analisis ini mendapati min dan varian untuk kesemua tempoh masa adalah ciri yang signifikan. Model pembelajaran mesin seperti DA, SVM, k -NN, Pokok Keputusan (Tree), Regresi Logistik (LR), Pokok Hutan Rawak (RF), Rangkaian Neural (NN), dinilai untuk mencari model yang terbaik dalam proses pengelasan ikan melalui ciri min dan varian. Penyelidik mendapati k -NN mempunyai prestasi terbaik dalam pengelasan tersebut dengan kejituhan 96.47%. Untuk memperhalusi ketepatan model k -NN ini, hiperparameter telah dioptimumkan melalui Pengoptimuman Bayesian. Hasil pengoptimuman ini, penyelidik mendapati hiperparameter terbaik adalah Jarak Standard Euclidean dengan nilai $k = 1$ yang memberikan 97.16% kejituhan pengelasan.

ABSTRACT

The understanding and identification of fish hunger behaviour are non-trivial in the aquaculture industry. This thesis aims at classifying the hunger state of *Lates Calcarifer* via the integration of computer vision and machine learning. Prior to the classification of the hunger states, the hunger state of the fish is identified through the k -means clustering technique and it was established that the hunger state could be demarcated into either ‘Hungry’ or ‘Satiated’. Upon the identification of the hunger state, significant features that could contribute towards the accurate classification of the states are investigated. The aforesaid features are analysed by the box plot analysis and the Principal Component Analysis (PCA). The established features are COG x, COG y and the moving summation of the pixel. Different machine learning models were investigated by incorporating the identified features, i.e., Discriminant Analysis (DA), Support Vector Machine (SVM) and k -Nearest Neighbours (k -NN) and it was demonstrated that the SVM trained model is able to classify up to 99.00%, suggesting that the developed system is viable for fish farming. A supplementary analysis was further carried out to understand the circadian rhythm of the fish by evaluating the time-series features. Different window sizes ranging from 0.5 min, 1.0 min, 1.5 min and 2.0 min coupled with the mean, maximum, minimum and variance for each of the distinctive temporal window sizes are investigated. PCA and PCA varimax rotation was employed in order to identify the best features through classifying it via SVM and k -NN. It was shown that the mean and variance of all temporal sizes are significant. In addition, the efficacy of different models based on the identified secondary features, namely DA, SVM, k -NN, Decision Tree (Tree), Logistic Regression (LR), Random Forest Tree (RF) and Neural Network (NN) are evaluated. It was found that the k -NN yielded the highest classification accuracy with 96.47% from the test sets. In order to further refine the k -NN model developed, hyperparameter optimization by means of Bayesian Optimization was carried out. Through the optimization process, the best hyperparameters that could attain a classification accuracy of 97.16% are the Standardized Euclidean distance metric with a k value of one.

TABLE OF CONTENT

DECLARATION

TITLE PAGE

ACKNOWLEDGEMENTS	ii
-------------------------	-----------

ABSTRAK	iii
----------------	------------

ABSTRACT	iv
-----------------	-----------

TABLE OF CONTENT	v
-------------------------	----------

LIST OF TABLES	ix
-----------------------	-----------

LIST OF FIGURES	xi
------------------------	-----------

LIST OF SYMBOLS	xiv
------------------------	------------

LIST OF ABBREVIATIONS	xv
------------------------------	-----------

CHAPTER 1 INTRODUCTION	1
-------------------------------	----------

1.1 Research Background	1
-------------------------	---

1.2 The Importance of the Topic	6
---------------------------------	---

1.3 Problem Statement	7
-----------------------	---

1.4 Research Hypotheses	8
-------------------------	---

1.5 Research Objective	9
------------------------	---

1.6 Research Scope	9
--------------------	---

1.7 Summary and Thesis Outline	10
--------------------------------	----

CHAPTER 2 LITERATURE REVIEW	12
------------------------------------	-----------

2.1 Introduction	12
------------------	----

2.2 Fish hunger behaviour	12
---------------------------	----

2.3	Automated Demand Feeder	17
2.4	Integrated systems in monitoring fish feeding pattern	19
2.5	ML techniques in fish parameters	29
2.6	Summary	35
CHAPTER 3 MATERIALS AND METHODOLOGY		37
3.1	Introduction	37
3.2	Project Framework	38
3.3	Automated Feeder Development	40
3.3.1	Conceptual design	40
3.3.2	Material and Function	41
3.4	Demand Feeder System with Image Processing	46
3.4.1	Image Processing System Design	47
3.4.2	Image Processing and Parameters Extraction	48
3.5	Experimental Setup	53
3.5.1	Image data acquisition	56
3.6	Machine Learning (ML) Techniques	58
3.6.1	Data pre-processing	60
3.6.2	Features Analysis and selection	63
3.6.3	Event Identification and Second Layer Features	66
3.6.4	Classification models	67
3.6.5	Classification Accuracy Rate Evaluation	73
3.6.6	Hyperparameter Tuning	75
3.7	Summary	76

CHAPTER 4 RESULTS AND DISCUSSION	77
4.1 Introduction	77
4.2 Automatic Feeder and Image Processing data	78
4.2.1 Specific Growth Rate	79
4.3 Analysis of ML Technique	81
4.3.1 Pre-processing and Clustering	81
4.3.2 Classification Models	83
4.3.3 Feature Selection	89
4.3.4 Classification Model's Comparison on Feature Selection	91
4.3.5 Remarks on Analysis of Proposed Methods on the Datasets	94
4.4 Investigation on Time-series Identification	95
4.4.1 Event Identification	96
4.4.2 Feature Selection PCA based	99
4.4.3 Comparing the Classification Rate	103
4.4.4 Hyperparameter Tuning	106
4.5 Summary	113
CHAPTER 5 CONCLUSION	115
5.1 Summary of the Main Findings	115
5.1.1 Objective 1: Parameters Contributing in Fish Behaviour	115
5.1.2 Objective 2: Determine Relevant Time-series Features of Hunger State	115
5.1.3 Objective 3: Evaluate ML technique on classifying hunger behaviour	116
5.2 The Contribution of the Study	116
5.3 Future works and Recommendation	117

REFERENCES	118
APPENDIX A AUTOMATED FEEDER DRAWINGS	127
APPENDIX B CIRCUIT DIAGRAM OF AUTOMATIC FEEDER	131
APPENDIX C SELECTION OF COLLECTED DATA FROM ROBOREALM	132
APPENDIX D SELECTION OF SECOND LAYER FEATURES FOR DAY 1	133
APPENDIX E SELECTION OF DATASETS OF EIGHT FEATURES	134
APPENDIX F SCATTERPLOT OF FEATURES	135
APPENDIX G NEURAL NETWORK PERFORMANCE	137
APPENDIX H PUBLICATIONS	140

LIST OF TABLES

Table 1.1	Projection of captured fish in ‘000 metric tonne (Fisheries Department of Malaysia, 2016)	2
Table 2.1	Summary of system monitoring on fish patterns	26
Table 2.2	Summary of ML techniques in the application of fisheries	33
Table 3.1	Component for demand feeder device with the image processing system	41
Table 3.2	Parameters descriptions gathered from computer vision	49
Table 3.3	Parameters descriptions gathered from computer vision	52
Table 3.4	Steps of k -means	62
Table 4.1	Comparing k -means for different sampling time on first day dataset	82
Table 4.2	Cluster results when $k = 2$ of first day	83
Table 4.3	Supervised learning datasets of first day	84
Table 4.4	Precision, recall, F_1 score and accuracy of the trained model of 0.33Hz	85
Table 4.5	Precision, recall, F_1 score and accuracy of the test set	87
Table 4.6	Precision, recall, F_1 score and accuracy between train and test set for DTW data	87
Table 4.7	Confusion Matrix comparison between Raw and DTW on test data	88
Table 4.8	Precision, recall, F_1 score and accuracy between different mode of the test set for third day data	92
Table 4.9	Precision, recall, F_1 score and accuracy between different modes of the test set for second and third day data	94
Table 4.10	Factor Loading after Varimax rotation	101
Table 4.11	MSE using SVM	102
Table 4.12	Parameters of the classification models	104
Table 4.13	Test set error on selected models	105

Table 4.14	MSE using k -NN model on train set	107
Table 4.15	MSE using k -NN model on test set	107
Table 4.16	Objective function results on the best possible outcome for k -NN 16 features	109
Table 4.17	Objective function results on the best possible outcome for k -NN two dimensions PCA	111
Table 4.18	Objective function results on the best possible outcome for k -NN eight features of PCA Varimax	112
Table 4.19	MSE using k -NN model on train set after hyperparameter tuning	113
Table 4.20	MSE using k -NN model on validation set after hyperparameter tuning	113

LIST OF FIGURES

Figure 2.1	Swimming behaviour patterns	14
Figure 2.2	Schematic diagram of integrated monitoring system with feeder	18
Figure 3.1	Experiment Flowchart	39
Figure 3.2	Conceptual design of the automated feeder	40
Figure 3.3	Integration of the automated feeder system with IR sensor	42
Figure 3.4	Bluno M3	42
Figure 3.5	A4988 Stepper Motor Driver Carrier wiring diagram	43
Figure 3.6	Stepper Motor Driver Carrier	44
Figure 3.7	Photoelectric sensor	44
Figure 3.8	<i>Lates calcarifer</i> species	45
Figure 3.9	DCS-936L Camera	46
Figure 3.10	Schematic diagram of the automated feeder system	47
Figure 3.11	Image and feeder schematic system	48
Figure 3.12	Image cropping	49
Figure 3.13	Image contrast	50
Figure 3.14	Image Thresholding	50
Figure 3.15	Image of COG of a frame	51
Figure 3.16	Experiment Setup	53
Figure 3.17	Camera position capturing fish tank front view setup	54
Figure 3.18	Automated feeder system model setup	54
Figure 3.19	Fish location (a) Fishes during triggering the sensor (b) Fishes at free running state	55
Figure 3.20	Demand feeder with test subjects of <i>Lates Calcarifer</i> captured using the camera on Roborealm	57
Figure 3.21	Serial communication between Bluno M3 and Roborealm	57

Figure 3.22	Machine Learning techniques flowchart	59
Figure 3.23	Bloxpots annotation	64
Figure 3.24	Decision tree model assumption on fish hunger	71
Figure 3.25	Confusion Matrix table	74
Figure 4.1	Data collected of first day into MATLAB	78
Figure 4.2	Data collected of first day from Excel into MATLAB	79
Figure 4.3	SGR percentage between feeder (a) body weight (b) total length.	80
Figure 4.4	DTW for BOX_SIZE feature between first and second day	82
Figure 4.5	Training set of first day (a) Classification accuracy for 1Hz data (b) Accuracy for 0.33Hz data with a comparison between SMA and both SMA-DTW	84
Figure 4.6	Classification accuracy of test data second day	86
Figure 4.7	Boxplots comparisons in a scale [0 1] for all the features	90
Figure 4.8	Pixels scale for selected features	90
Figure 4.9	Test data classification accuracy of Original, Normalize and PCA	92
Figure 4.10	Test data of second day and third day classification accuracy compared with using PCA	93
Figure 4.11	Extracting temporal window for feeding process	97
Figure 4.12	Accuracy error (a) Variation of sample sizes for given window size (b) Differences in window size on 50mins and 60 mins sample size	98
Figure 4.13	PCA results without varimax rotation	100
Figure 4.14	Scree plot of the features	100
Figure 4.15	Classification accuracy for various models on test set	105
Figure 4.16	Functions evaluation observed for k -NN 16 features	108
Figure 4.17	Objective functions evaluation observed for k -NN 16 features	108
Figure 4.18	Two dimensions of PCA dataset (a) Function evaluation observed (b) Objective functions evaluation observed	110

Figure 4.19 Eight features of PCA Varimax dataset (a) Function evaluation observed (b) Objective functions evaluation observed 110

LIST OF SYMBOLS

c	Summation of distance
d	Euclidean distance
i	Sequence number
j	Sequence number
k	Number of neighbors
l	Sequence number
$u(t)$	Time series first warped signal
$v(t)$	Time series second warped signal
x	Points of cluster
y	Points of cluster
z	Input parameter of sigmoid
C	Total distance
C_i	Mean
D	Warping path distance
N	Total number of data points
R	Repeatability score
U	Time series first signal
V	Time series second signal
ξ	Warping path
ρ	Euclidean distance
ξ_i	Loss term
μ	Mean
\mathbb{R}	Set of real number
ϕ	Sigmoid function
Θ	Radian

LIST OF ABBREVIATIONS

3D	Three Dimensional
AI	Artificial Intelligence
ANN	Artificial Neural Network
BCT	Black Chinned Tilapia
CART	Classification and Regression Tree
CCD	Charge Coupled Device
COG	Centre of Gravity
CV	Cross Validation
DA	Discriminant Analysis
DTW	Dynamic Time Warping
EMG	Electromyography
F ₁	F ₁ Score
FP	False Positive
FN	False Negative
IR	Infrared
k-NN	K-Nearest Neighbors
LR	Logistic Regression
ML	Machine Learning
MSE	Mean Squared Error
NaN	Not-a-Number
NT	Nile Tilapia
OFT	Open Field Test
PCA	Principal Component Analysis
RF	Random Forest Tree
SGR	Specific Growth Rate
SMA	Simple Moving Average
SMO	Sequential Minimal Optimization
SMBO	Sequential Model Based Optimization
SVM	Support Vector Machine
TP	True Positive
TN	True Negative

REFERENCES

- Alanara, A. (1992). The effect of time-restricted demand feeding on feeding activity growth and feed conversion in rainbow trout (*Oncorhynchus mykiss*). *Aquaculture*, 108(3–4), 357–368. Retrieved from <http://www.sciencedirect.com/science/article/B6T4D-49KSW8F-6W/2/48d533443634e6b3d7bcd6fd8cd4e486>
- Allken, V., Handegard, N. O., Rosen, S., Schreyeck, T., Mahiout, T., & Malde, K. (2019). Fish species identification using a convolutional neural network trained on synthetic data. *ICES Journal of Marine Science*, 76(1), 342–349. <https://doi.org/10.1093/icesjms/fsy147>
- Alós, J., Martorell-Barceló, M., & Campos-Candela, A. (2017). Repeatability of circadian behavioural variation revealed in free-ranging marine fish. *Royal Society Open Science*, 4(2), 160791. <https://doi.org/10.1098/rsos.160791>
- Amano, M., Iigo, M., Sunuma, T., Yamashita, M., Furukawa, K., Tabata, M., & Yamamori, K. (2007). Development of new self-feeding system for mass rearing of ayu *Plecoglossus altivelis altivelis* under artificial and natural light-dark cycles. *Fisheries Science*, 73(4), 800–807. <https://doi.org/10.1111/j.1444-2906.2007.01399.x>
- Ariyomo, T. O., & Watt, P. J. (2015). Effect of hunger level and time of day on boldness and aggression in the zebrafish *Danio rerio*. *Journal of Fish Biology*, 86(6), 1852–1859. <https://doi.org/10.1111/jfb.12674>
- Aschoff, J. (1960). Exogenous and endogenous components in circadian rhythms. *Cold Spring Harb Symp Quant Biol.*, 25, 11–28.
- Azzaydi, M., Madrid, J. , Zamora, S., Sánchez-Vázquez, F., & Martínez, F. (1998). Effect of three feeding strategies (automatic, ad libitum demand-feeding and time-restricted demand-feeding) on feeding rhythms and growth in European sea bass (*Dicentrarchus labrax* L.). *Aquaculture*, 163(3–4), 285–296. [https://doi.org/10.1016/S0044-8486\(98\)00238-5](https://doi.org/10.1016/S0044-8486(98)00238-5)
- Beale, A., Guibal, C., Tamai, T. K., Klotz, L., Cowen, S., Peyric, E., Whitmore, D. (2013). Circadian rhythms in Mexican blind cavefish *Astyanax mexicanus* in the lab and in the field. *Nature Communications*, 4(1), 2769. <https://doi.org/10.1038/ncomms3769>
- Benhaïm, D., Akian, D. D., Ramos, M., Ferrari, S., Yao, K., & Bégout, M. L. (2017). Self-feeding behaviour and personality traits in tilapia: A comparative study between *Oreochromis niloticus* and *Sarotherodon melanotheron*. *Applied Animal Behaviour Science*, 187, 85–92. <https://doi.org/10.1016/j.applanim.2016.12.004>

Bermejo, S. (2014). The benefits of using otolith weight in statistical fish age classification: A case study of Atlantic cod species. *Computers and Electronics in Agriculture*, 107, 1–7. <https://doi.org/10.1016/J.Compag.2014.06.001>

Biswas, G., Thirunavukkarasu, A. R., Sundaray, J. K., & Kailasam, M. (2010). Optimization of feeding frequency of Asian seabass (*Lates calcarifer*) fry reared in net cages under brackishwater environment. *Aquaculture*, 305(1), 26–31. <https://doi.org/http://dx.doi.org/10.1016/j.aquaculture.2010.04.002>

Boujard, T., & Leatherland, J. F. (1992). Circadian rhythms and feeding time in fishes. *Environmental Biology of Fishes*, 35(2), 109–131. <https://doi.org/10.1007/BF00002186>

Braithwaite, V. A., Rosenthal, G. G., & Lobel, P. S. (2006). Circadian Rhythms In Fish - Behaviour and Physiology of Fish: Volume 24, 197–238. [https://doi.org/DOI:10.1016/S1546-5098\(05\)24006-2](https://doi.org/DOI:10.1016/S1546-5098(05)24006-2)

Breiman, L. (2001). Random Forests. *Machine Learning*, 45(1), 5–32. <https://doi.org/10.1023/A:1010933404324>

Broell, F., Noda, T., Wright, S., Domenici, P., Steffensen, J. F., Auclair, J.-P., & Taggart, C. T. (2013). Accelerometer tags: detecting and identifying activities in fish and the effect of sampling frequency. *The Journal of Experimental Biology*, 216(Pt 7), 1255–64. <https://doi.org/10.1242/jeb.077396>

Buelens, B., Pauly, T., Williams, R., & Sale, A. (2009). Kernel methods for the detection and classification of fish schools in single-beam and multibeam acoustic data. *ICES Journal of Marine Science*, 66, 1130–1135. <https://doi.org/10.1093/icesjms/fsp004>

Burguera, A., & Oliver, G. (2016). High-resolution underwater mapping using Side-Scan Sonar. *PLoS ONE*, 11(1), 1–41. <https://doi.org/10.1371/journal.pone.0146396>

Cavallari, N., Frigato, E., Vallone, D., Fröhlich, N., Lopez-Olmeda, J. F., Foà, A., Foulkes, N. S. (2011). A Blind Circadian Clock in Cavefish Reveals that Opsins Mediate Peripheral Clock Photoreception. *PLoS Biology*, 9(9), e1001142. <https://doi.org/10.1371/journal.pbio.1001142>

Chang, C.-C., & Lin, C.-J. (2011). LIBSVM. *ACM Transactions on Intelligent Systems and Technology*, 2(3), 1–27. <https://doi.org/10.1145/1961189.1961199>

Chapman, B. B., Morrell, L. J., & Krause, J. (2010). Unpredictability in food supply during early life influences boldness in fish. *Behavioral Ecology*, 21(3), 501–506. Retrieved from <http://dx.doi.org/10.1093/beheco/arq003>

- Cho, C. Y. (1992). Feeding systems for rainbow trout and other salmonids with reference to current estimates of energy and protein requirements. *Aquaculture*, 100(1–3), 107–123. [https://doi.org/10.1016/0044-8486\(92\)90353-M](https://doi.org/10.1016/0044-8486(92)90353-M)
- Cortes, C., & Vapnik, V. (1995). Support-Vector Networks. *Machine Learning*, 20(3), 273–297. <https://doi.org/10.1023/A:1022627411411>
- Covès, D., Beauchaud, M., Attia, J., Dutto, G., Bouchut, C., & Bégout, M. L. (2006). Long-term monitoring of individual fish triggering activity on a self-feeding system: An example using European sea bass (*Dicentrarchus labrax*). *Aquaculture*, 253(1–4), 385–392. <https://doi.org/10.1016/j.aquaculture.2005.08.015>
- Cubitt, K. F., Williams, H. T., Rowsell, D., McFarlane, W. J., Gosine, R. G., Butterworth, K. G., & McKinley, R. S. (2008). Development of an intelligent reasoning system to distinguish hunger states in Rainbow trout (*Oncorhynchus mykiss*). *Computers and Electronics in Agriculture*, 62(1), 29–34. <https://doi.org/10.1016/j.compag.2007.08.010>
- Dangeti, P. (2017). Statistics for Machine Learning Build supervised, unsupervised, and reinforcement learning models using both Python and R. Packt Publishing. Retrieved from www.packtpub.com
- Dutta, M. K., Sengar, N., Kamble, N., Banerjee, K., Minhas, N., & Sarkar, B. (2016). Image processing based technique for classification of fish quality after cypermethrine exposure. *LWT - Food Science and Technology*, 68, 408–417. <https://doi.org/10.1016/J.LWT.2015.11.059>
- Fisheries Department of Malaysia. (2016). Landings Of Marine Fish By Tonnage Class And Fishing Gear Group. Retrieved from https://www.dof.gov.my/dof2/resources/user_29/Documents/Perangkaan Perikanan/2016/Kumulatif.pdf
- Føre, M., Frank, K., Svendsen, E., Alfredsen, J. A., Dempster, T., Eguiraun, H., Alver, M. O. (2018). Precision fish farming: A new framework to improve production in aquaculture. *Biosystems Engineering*, 173, 176–193. <https://doi.org/10.1016/J.BioSystemsEng.2017.10.014>
- Fransen, B. R., Duke, S. D., McWethy, L. G., Walter, J. K., & Bilby, R. E. (2006). A Logistic Regression Model for Predicting the Upstream Extent of Fish Occurrence Based on Geographical Information Systems Data. *North American Journal of Fisheries Management*, 26(4), 960–975. <https://doi.org/10.1577/M04-187.1>
- Gastauer, S., Scoulding, B., & Parsons, M. (2017). An Unsupervised Acoustic Description of Fish Schools and the Seabed in Three Fishing Regions Within the Northern Demersal Scalefish Fishery (NDSF, Western Australia). *Acoustics Australia*, 45(2), 363–380. <https://doi.org/10.1007/s40857-017-0100-0>

- Guan, J., Liu, H., Shi, X., Feng, S., & Huang, B. (2017). Tracking Multiple Genomic Elements Using Correlative CRISPR Imaging and Sequential DNA FISH. *Biophysical Journal*, 112(6), 1077–1084. <https://doi.org/10.1016/J.BPJ.2017.01.032>
- Guralnik, V., & Srivastava, J. (1999). Event detection from time series data. In Proceedings of the fifth ACM SIGKDD international conference on Knowledge discovery and data mining - KDD '99 (pp. 33–42). New York, New York, USA: ACM Press. <https://doi.org/10.1145/312129.312190>
- Gurney, K., & York, N. (1997). An introduction to neural networks. Bristol, PA, USA: Taylor & Francis, Inc. Retrieved from https://www.inf.ed.ac.uk/teaching/courses/nlu/assets/reading/Gurney_et_al.pdf
- Handoko, Y., Nazaruddin, Y. Y., & Hu, H. (2009). Using Echo Ultrasound from Schooling Fish to Detect and Classify Fish Types. *Journal of Bionic Engineering*, 6(3), 264–269. [https://doi.org/10.1016/S1672-6529\(08\)60120-1](https://doi.org/10.1016/S1672-6529(08)60120-1)
- Hansen, M. J., Schaerf, T. M., & Ward, A. J. W. (2015). The effect of hunger on the exploratory behaviour of shoals of mosquitofish *Gambusia holbrooki*. *Behaviour*, 152(12–13), 1659–1677. <https://doi.org/10.1163/1568539X-00003298>
- Harpaz, S., Hakim, Y., Barki, A., Karplus, I., Slosman, T., & Tufan Eroldogan, O. (2005). Effects of different feeding levels during day and/or night on growth and brush-border enzyme activity in juvenile *Lates calcarifer* reared in freshwater recirculating tanks. *Aquaculture*, 248(1), 325–335. <https://doi.org/http://dx.doi.org/10.1016/j.aquaculture.2005.04.033>
- Hasija, S., Buragohain, M. J., & Indu, S. (2017). Fish Species Classification Using Graph Embedding Discriminant Analysis. In 2017 International Conference on Machine Vision and Information Technology (CMVIT): 17-19 February 2017, Singapore (pp. 81–86). IEEE. <https://doi.org/10.1109/CMVIT.2017.23>
- Hastie, T., Tibshirani, R., & Friedman, J. (2001). The Elements of Statistical Learning. *The Mathematical Intelligencer*, 27(2), 83–85. <https://doi.org/10.1198/jasa.2004.s339>
- Isvari, N. M. S., Wella, & Ranny. (2017). Fish freshness classification method based on fish image using k-Nearest Neighbor. In 2017 4th International Conference on New Media Studies (CONMEDIA): 8-10 November 2017, Yogyakarta, Indonesia (pp. 87–91). IEEE. <https://doi.org/10.1109/CONMEDIA.2017.8266036>
- Jackson, D. A., Walker, S. C., & Poos, M. S. (2010). Cluster Analysis of Fish Community Data: "New" Tools for Determining Meaningful Groupings of Sites and Species Assemblages. American Fisheries Society Symposium, 73, 503–527. Retrieved from http://jackson.eeb.utoronto.ca/files/2012/10/2010_Jackson_Walker_Poos_StreamFi

shCommunities.pdf

- Jolles, J. W., Manica, A., & Boogert, N. J. (2016). Brief Communication Food intake rates of inactive fish are positively linked to boldness in three-spined sticklebacks *Gasterosteus aculeatus*. *Journal of Fish Biology*. <https://doi.org/10.1111/jfb.12934>
- Jolliffe, I. T. (2002). Principal Component Analysis. Second Edition. Springer Series in Statistics, 98, 487. <https://doi.org/10.2307/1270093>
- Kadri, S., Metcalfe, N. B., Huntingford, F. A., & Thorpe, J. E. (1997). Daily feeding rhythms in Atlantic salmon I: feeding and aggression in parr under ambient environmental conditions. *Journal of Fish Biology*, 50(2), 267–272. <https://doi.org/10.1111/j.1095-8649.1997.tb01357.x>
- Kennedy, J., Jónsson, S. Þ., Ólafsson, H. G., & Kasper, J. M. (2016). Observations of vertical movements and depth distribution of migrating female lumpfish (Cyclopterus lumpus) in Iceland from data storage tags and trawl surveys. *ICES Journal of Marine Science: Journal Du Conseil*, 73(4), 1160–1169. <https://doi.org/10.1093/icesjms/fsv244>
- Khuller, S., Rosenfeld, A., & Wu, A. (2000). Centers of sets of pixels. *Discrete Applied Mathematics*, 103(1–3), 297–306. [https://doi.org/10.1016/S0166-218X\(99\)00248-6](https://doi.org/10.1016/S0166-218X(99)00248-6)
- Klein, A., Falkner, S., Bartels, S., Hennig, P., & Hutter, F. (2016). Fast Bayesian Optimization of Machine Learning Hyperparameters on Large Datasets. In 20th International Conference on Artificial Intelligence and Statistics (AISTATS) 20–22 April 2017, Fort Lauderdale, Florida, USA. JMLR: W&CP volume 54. Retrieved from <http://arxiv.org/abs/1605.07079>
- Liu, Z., Li, X., Fan, L., Lu, H., Liu, L., & Liu, Y. (2014). Measuring feeding activity of fish in RAS using computer vision. *Aquacultural Engineering*, 60, 20–27. <https://doi.org/10.1016/J.Aquaeng.2014.03.005>
- Malaysia Fish Development Agency. (2017). Report Marketing Market. Retrieved from <http://www.lkim.gov.my/wp-content/uploads/2015/10/Buku-Laporan-Risikan-Pasaran-Tahunan-2017.pdf>
- Marini, S., Corgnati, L., Mantovani, C., Bastianini, M., Ottaviani, E., Fanelli, E., Poulain, P.-M. (2018). Automated estimate of fish abundance through the autonomous imaging device GUARD1. *Measurement*, 126, 72–75. <https://doi.org/10.1016/J.Measurement.2018.05.035>
- Mattos, B. O. de, Filho, E. C. T. N., Barreto, K. A., Braga, L. G. T., & Fortes-Silva, R. (2016). Self-feeder systems and infrared sensors to evaluate the daily feeding and locomotor rhythms of Pirarucu (*Arapaima gigas*) cultivated in outdoor tanks. *Aquaculture*, 457, 118–123. <https://doi.org/10.1016/J.Aquaculture.2016.02.026>

- Močkus, J. (1975). On bayesian methods for seeking the extremum. In Proceedings of the IFIP Technical Conference (pp. 400–404). Springer-Verlag, Berlin, Heidelberg. https://doi.org/10.1007/3-540-07165-2_55
- Morel, M., Achard, C., Kulpa, R., & Dubuisson, S. (2018). Time-series averaging using constrained dynamic time warping with tolerance. *Pattern Recognition*, 74, 77–89. <https://doi.org/10.1016/J.Patcog.2017.08.015>
- Mukai, Y., Tan, N. H., Khairulanwar, M., Chung, R. &, & Liau, F. (2016). Demand Feeding System Using an Infrared Light Sensor for Brown-marbled Grouper Juveniles, *Epinephelus fuscoguttatus*. *Sains Malaysiana*, 45(5), 729–733. Retrieved from http://journalarticle.ukm.my/9875/1/08_Yukinori_Mukai.pdf
- Nakayama, S., Johnstone, R. A., & Manica, A. (2012). Temperament and Hunger Interact to Determine the Emergence of Leaders in Pairs of Foraging Fish. *PLoS ONE*, 7(8), e43747. <https://doi.org/10.1371/journal.pone.0043747>
- Navarro-Guillén, C., Yúfera, M., & Engrola, S. (2017). Daily feeding and protein metabolism rhythms in Senegalese sole post-larvae. *Biology Open*, 6(1), 77–82. <https://doi.org/10.1242/bio.021642>
- Ogunlana, S. O., Olabode, O., Oluwadare, S. A. A., & Iwasokun, G. B. (2015). Fish Classification Using Support Vector Machine. *African Journal of Computing & ICT African Journal of Computing & ICT Reference Format: Afr J. of Comp & ICTs*, 8(2), 75–82. Retrieved from www.ajocict.net
- Ogunlela, A. O., & Adebayo, A. A. (2016). Development and Performance Evaluation of an Automatic Fish Feeder. *Journal of Aquaculture Research & Development*, 07(02), 1–4. <https://doi.org/10.4172/2155-9546.1000407>
- Otaki, T., Miyamoto, Y., Amakasu, K., Uchida, K., & Sasakura, T. (2011). Development of a sonar-responding acoustic tag for fish behavior observation. In 2011 IEEE Symposium on Underwater Technology and Workshop on Scientific Use of Submarine Cables and Related Technologies (pp. 1–4). IEEE. <https://doi.org/10.1109/UT.2011.5774085>
- Parra, L., García, L., Sendra, S., & Lloret, J. (2018). The Use of Sensors for Monitoring the Feeding Process and Adjusting the Feed Supply Velocity in Fish Farms. *Journal of Sensors*, 2018, 1–14. <https://doi.org/10.1155/2018/1060987>
- Parra, L., Sendra, S., García, L., & Lloret, J. (2018). Design and Deployment of Low-Cost Sensors for Monitoring the Water Quality and Fish Behavior in Aquaculture Tanks during the Feeding Process. *Sensors*, 18(3), 750. <https://doi.org/10.3390/s18030750>

- Peré-Trepat, E., Olivella, L., Ginebreda, A., Caixach, J., & Tauler, R. (2006). Chemometrics modelling of organic contaminants in fish and sediment river samples. *Science of the Total Environment*, 371, 223–237. <https://doi.org/10.1016/j.scitotenv.2006.04.005>
- Pillay, T. V. R., & Kutty, M. N. (2005). Aquaculture: principles and practices. *Aquaculture: principles and practices*. Blackwell Publishing. Retrieved from <https://www.cabdirect.org/cabdirect/abstract/20053169629>
- Pohar, M., Blas, M., & Turk, S. (2004). Comparison of Logistic Regression and Linear Discriminant Analysis: A Simulation Study. *Metodološki Zvezki*, 1(1), 143–161. Retrieved from <https://www.stat-d.si/mz/mz1.1/pohar.pdf>
- Priyadarshana, T., Asaeda, T., & Manatunge, J. (2006). Hunger-induced foraging behavior of two cyprinid fish: *Pseudorasbora parva* and *Rasbora daniconius*. *Hydrobiologia*, 568(1), 341–352. <https://doi.org/10.1007/s10750-006-0201-5>
- Rahman, M. M., Nagelkerke, L. A. J., Verdegem, M. C. J., Wahab, M. A., & Verreth, J. A. J. (2008). Relationships among water quality, food resources, fish diet and fish growth in polyculture ponds: A multivariate approach. *Aquaculture*, 275(1–4), 108–115. <https://doi.org/10.1016/J.Aquaculture.2008.01.027>
- Razman, M. A. M., Susto, G. A., Cenedese, A., Abdul Majeed, A. P. P., Musa, R. M., Abdul Ghani, A. S., ... Mukai, Y. (2019). Hunger classification of *Lates calcarifer* by means of an automated feeder and image processing. *Computers and Electronics in Agriculture*, 163, 104883. <https://doi.org/10.1016/J.Compag.2019.104883>
- Robotham, H., Castillo, J., Bosch, P., & Perez-Kallens, J. (2011). A comparison of multi-class support vector machine and classification tree methods for hydroacoustic classification of fish-schools in Chile. *Fisheries Research*, 111(3), 170–176. <https://doi.org/10.1016/J.Fishres.2011.07.010>
- Rose, C. S., Stoner, A. W., & Matteson, K. (2005). Use of high-frequency imaging sonar to observe fish behaviour near baited fishing gears. *Fisheries Research*, 76(2), 291–304. <https://doi.org/10.1016/j.fishres.2005.07.015>
- Sanchez-Vázquez, F. J., Madrid, J. A., & Zamora, S. (1995). Circadian Rhythms of Feeding Activity in Sea Bass, *Dicentrarchus labrax* L.: Dual Phasing Capacity of Diel Demand-Feeding Pattern. *Journal of Biological Rhythms*, 10(3), 256–266. <https://doi.org/10.1177/074873049501000308>
- Scandol, J. (2005). Use of Quality Control Methods to Monitor the Status of Fish Stocks. In K. G (Ed.), *Fisheries Assessment and Management in Data-Limited Situations* (pp. 216–266). University of Alaska Fairbanks: Alaska Sea Grant. <https://doi.org/10.4027/famdl.2005>

Seltman, H. J. (2018). Experimental Design and Analysis. Carnegie Mellon University. Retrieved from <http://www.stat.cmu.edu/~hseltman/309/Book/Book.pdf>

Shalev-Shwartz, S., & Ben-David, S. (2013). Understanding machine learning: From theory to algorithms. Understanding Machine Learning: From Theory to Algorithms (Vol. 9781107057). <https://doi.org/10.1017/CBO9781107298019>

Siddiqui, S. A., Salman, A., Malik, M. I., Shafait, F., Mian, A., Shortis, M. R., & Harvey, E. S. (2018). Automatic fish species classification in underwater videos: exploiting pre-trained deep neural network models to compensate for limited labelled data. ICES Journal of Marine Science, 75(1), 374–389. <https://doi.org/10.1093/icesjms/fsx109>

Spampinato, C., Chen-Burger, Y.-H., Nadarajan, G., & Fisher, R. (2008). Detecting, Tracking and Counting Fish in Low Quality Unconstrained Underwater Videos (pp. 514–519). Retrieved from [https://www.research.ed.ac.uk/portal/en/publications/detecting-tracking-and-counting-fish-in-low-quality-unconstrained-underwater-videos\(0f58b71b-1561-4438-8d7e-97020b126d2f\).html](https://www.research.ed.ac.uk/portal/en/publications/detecting-tracking-and-counting-fish-in-low-quality-unconstrained-underwater-videos(0f58b71b-1561-4438-8d7e-97020b126d2f).html)

Sudana, M., Nalluri, R., Saisujana, T., K, H. R., & Swaminathan, V. (2017). An Efficient Feature Selection using Artificial Fish Swarm Optimization and SVM Classifier, (July), 412–416.

Swann, L. (1997). A Fish Farmer's Guide to Understanding Water Quality. In Aquaculture Extension (p. AS-503-511). Illinois-Indiana Sea Grant Program: Aquaculture Extension. Retrieved from <https://www.indianasoybean.com/images/stories/Workshops/WaterQuality/File 3B Water Quality.pdf>

Taha, Z., Razman, M. A. M., Adnan, F. A., Abdul Majeed, A. P. P., Musa, R. M., Abdul Ghani, A. S., ... Mukai, Y. (2018). The Identification of Hunger Behaviour of Lates Calcarifer Using k-Nearest Neighbour (pp. 393–399). Springer, Singapore. https://doi.org/10.1007/978-981-10-8788-2_35

Thida, M., Eng, H., & Chew, B. F. (2009). Automatic Analysis of Fish Behaviors and Abnormality Detection. In Proc. Iapr Machine Vision Applications, 8--18. Retrieved from <http://citeseerx.ist.psu.edu/viewdoc/summary?doi=10.1.1.392.2594>

Tian, X. Y., Cai, Q., & Zhang, Y. M. (2012). Rapid classification of hairtail fish and pork freshness using an electronic nose based on the PCA method. Sensors, 12(1), 260–277. <https://doi.org/10.3390/s120100260>

Tušer, M. M. (2013). Fish detection with modern sonar systems. School of Doctoral Studies in Biological Sciences Faculty of Science, PhD, 79 p.

- Valletta, J. J., Torney, C., Kings, M., Thornton, A., & Madden, J. (2017). Applications of machine learning in animal behaviour studies. *Animal Behaviour*, 124, 203–220. <https://doi.org/10.1016/J.Anbehav.2016.12.005>
- Volkoff, H., & Peter, R. E. (2006). Feeding Behavior of Fish and Its Control. *Zebrafish*, 3(2), 131–140. [https://doi.org/https://doi.org/10.1089/zeb.2006.3.131](https://doi.org/10.1089/zeb.2006.3.131)
- Volpato, G. L., Bovi, T. S., de Freitas, R. H. A., da Silva, D. F., Delicio, H. C., Giaquinto, P. C., & Barreto, R. E. (2013). Red light stimulates feeding motivation in fish but does not improve growth. *PLoS One*, 8(3), e59134. <https://doi.org/10.1371/journal.pone.0059134>
- Wishkerman, A., Boglino, A., Darias, M. J., Andree, K. B., Estévez, A., & Gisbert, E. (2016). Image analysis-based classification of pigmentation patterns in fish: A case study of pseudo-albinism in Senegalese sole. *Aquaculture*, 464, 303–308. <https://doi.org/10.1016/J.AQUACULTURE.2016.06.040>
- Xu, Z., & Cheng, X. E. (2017). Zebrafish tracking using convolutional neural networks. *Scientific Reports*, 7(1), 42815. <https://doi.org/10.1038/srep42815>
- Yassin, W., Rahayu, S., Abdollah, F., & Zin, H. (2016). An Improved Malicious Behaviour Detection Via k- Means and Decision Tree. *IJACSA) International Journal of Advanced Computer Science and Applications*, 7(12). Retrieved from www.ijacsai.thesai.org
- Zhou, C., Zhang, B., Lin, K., Xu, D., Chen, C., Yang, X., & Sun, C. (2017). Near-infrared imaging to quantify the feeding behavior of fish in aquaculture. *Computers and Electronics in Agriculture*, 135, 233–241. <https://doi.org/10.1016/j.compag.2017.02.013>